Chiller Control *Friday Seminar 2022-03-04* Christian Rosdahl





Cooperation with Carrier





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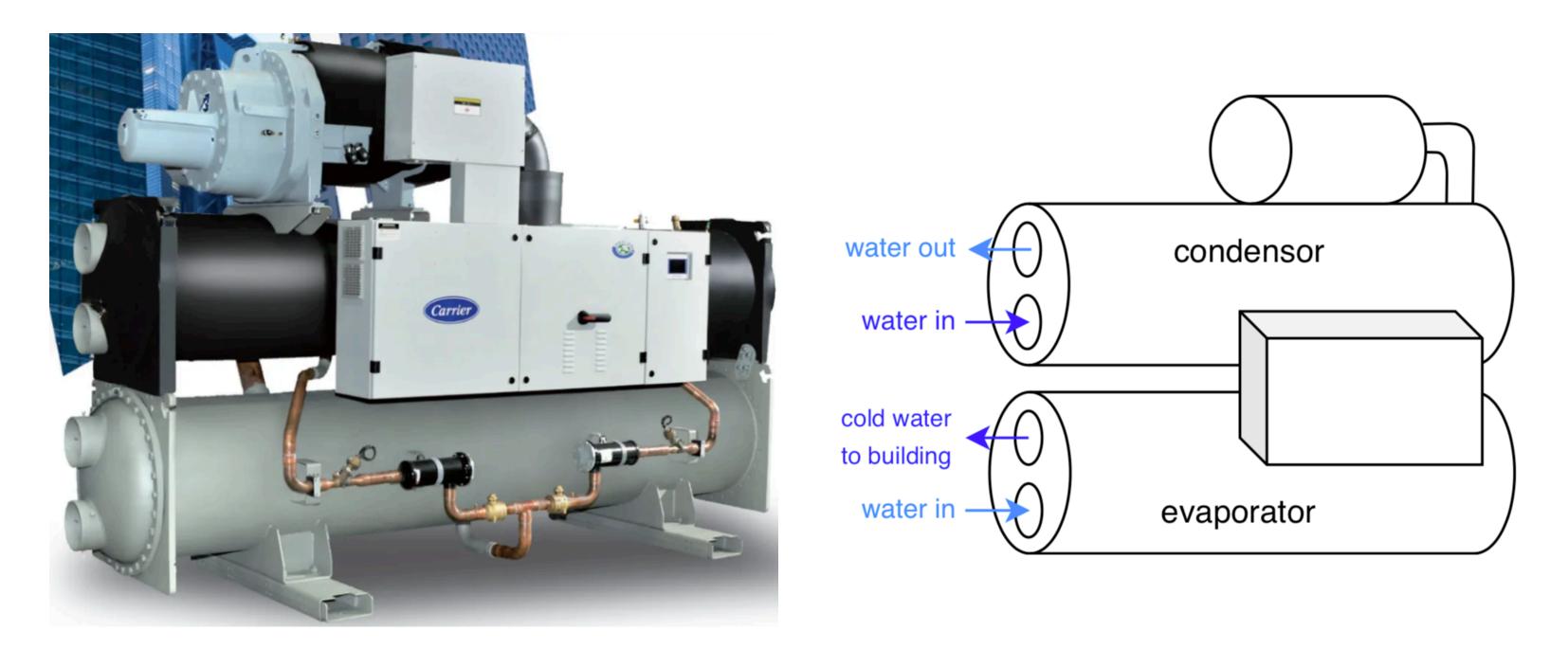
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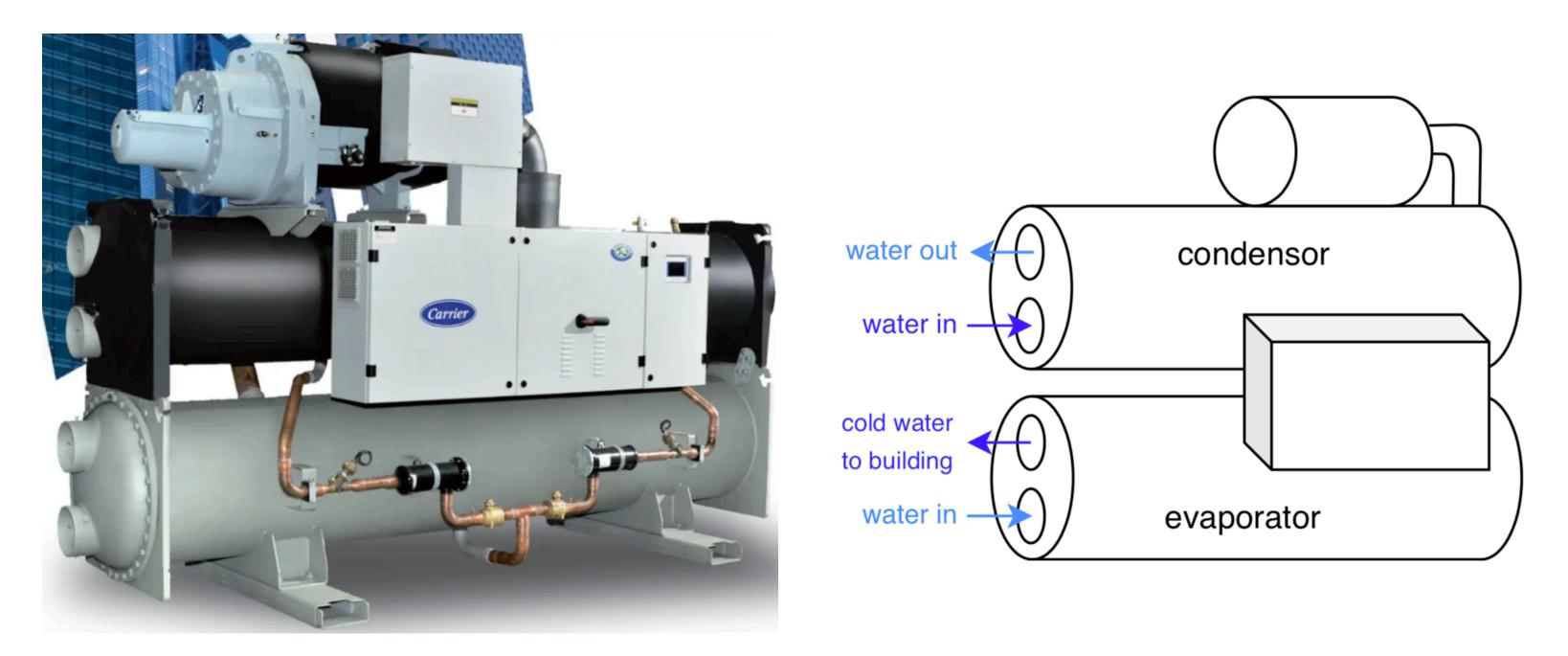


Thanks to

Bryan Eisenhower, Magda Atlevi and Clas Jacobson @ Carrier

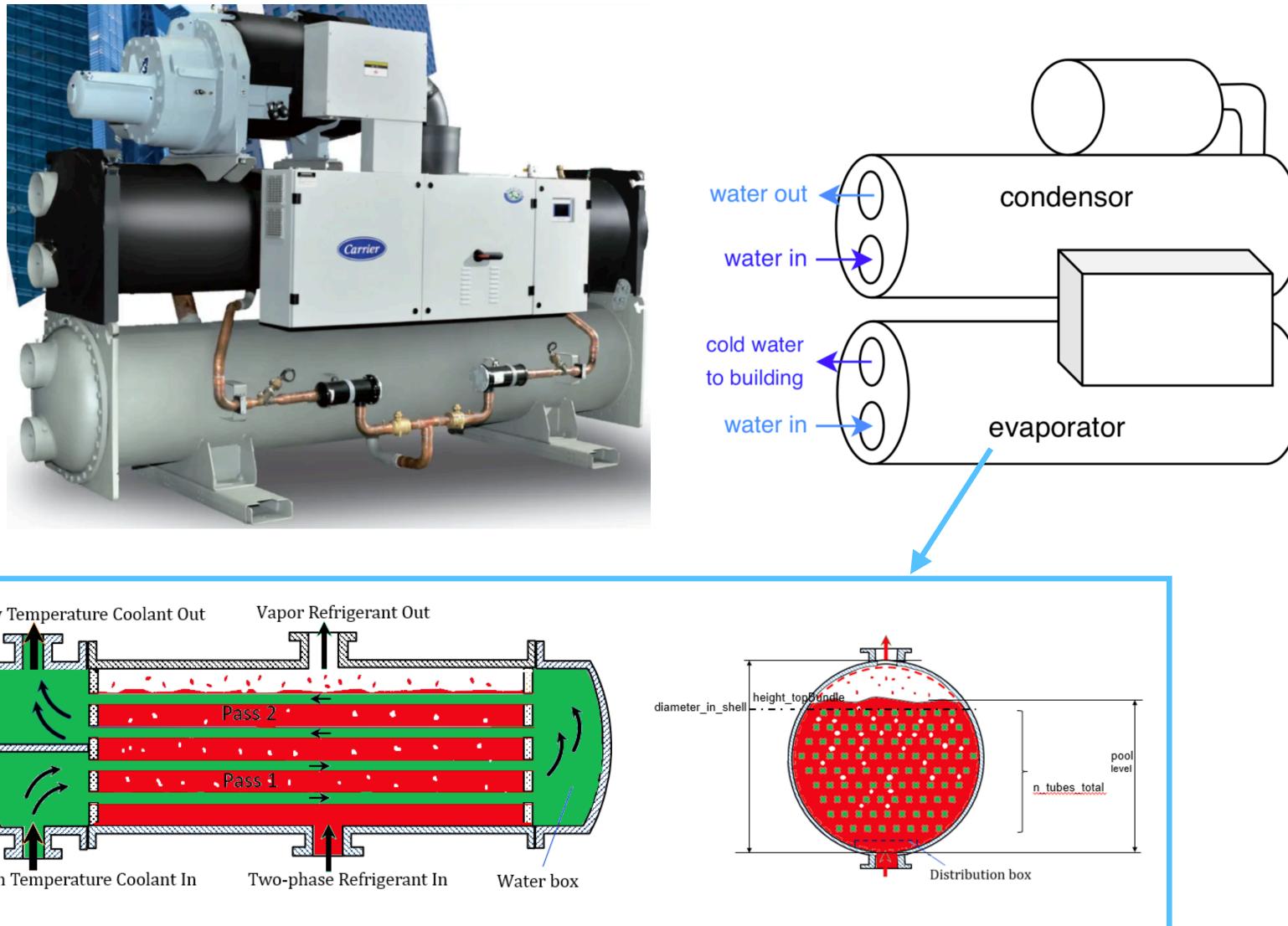


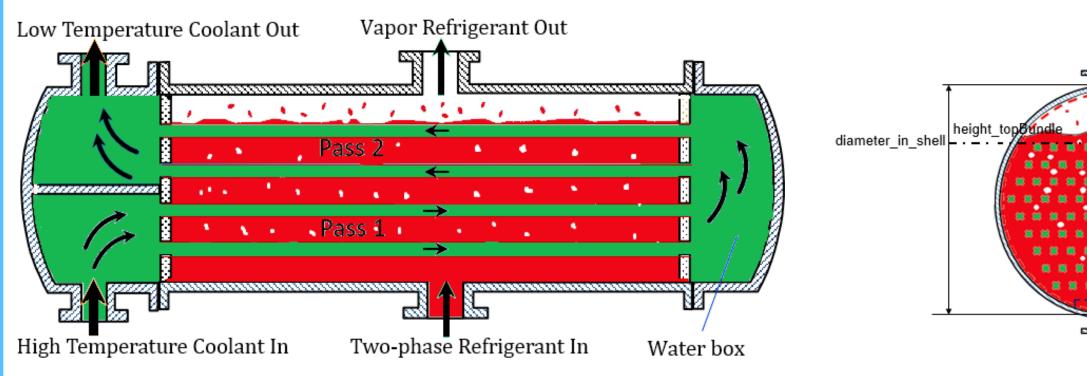




Goal: Cool down water to be used for cooling of buildings etc.

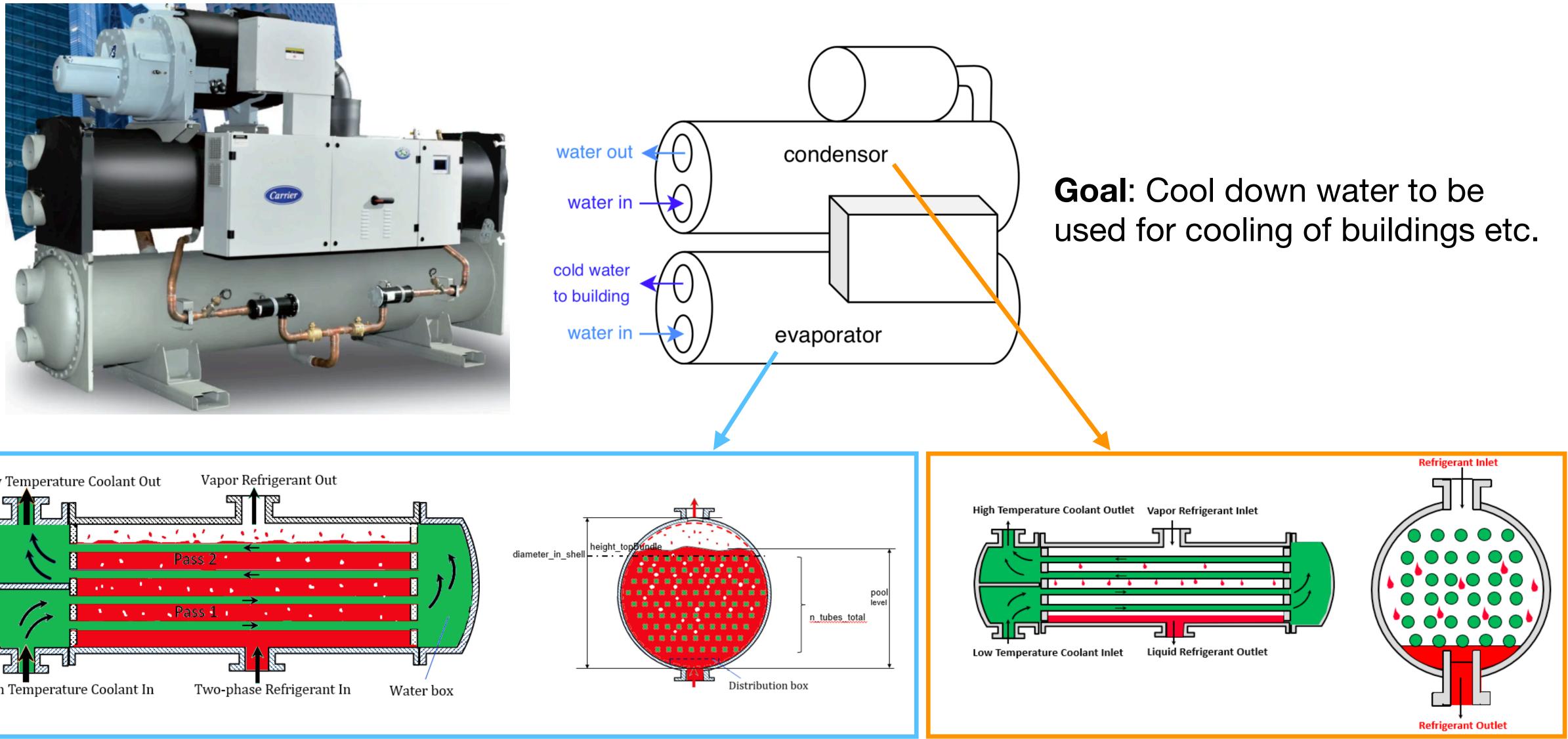


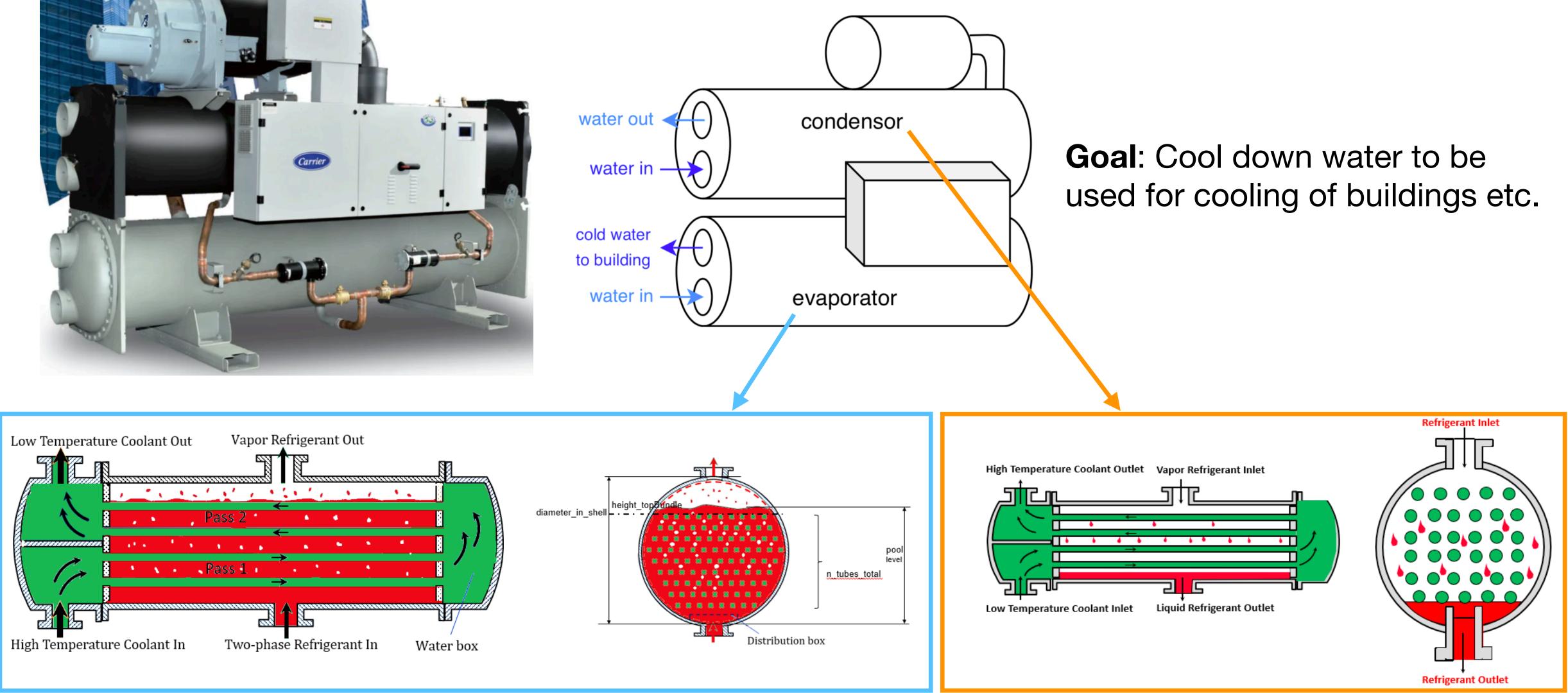




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Space cooling consumes about 1885 TWh per year, which is **about 8% of the world's total electricity consumption**. ^[1,2]

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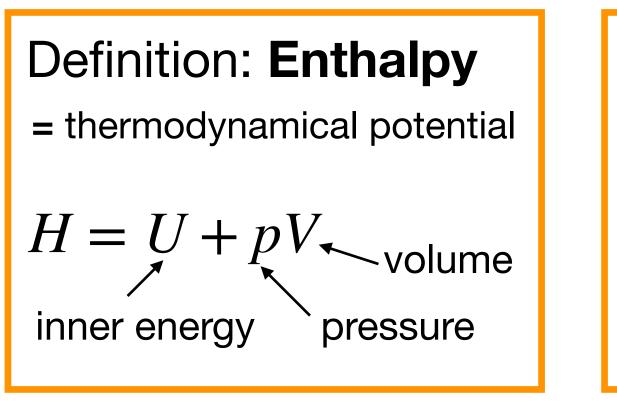
Question: Can we improve the efficiency by using machine learning methods?

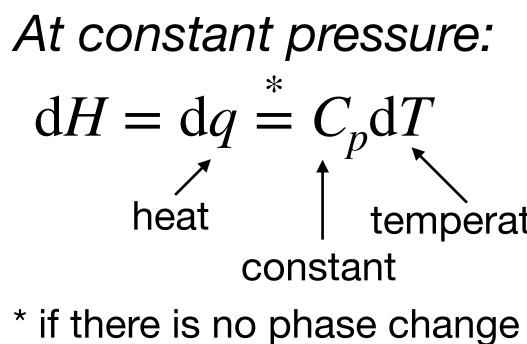
Definition: Enthalpy

= thermodynamical potential

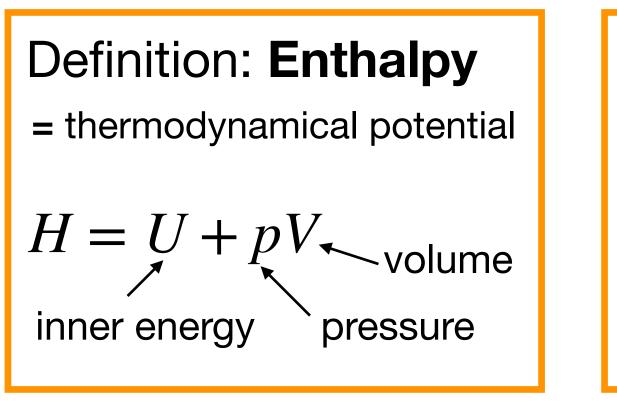
$$H = U + pV \text{volume}$$

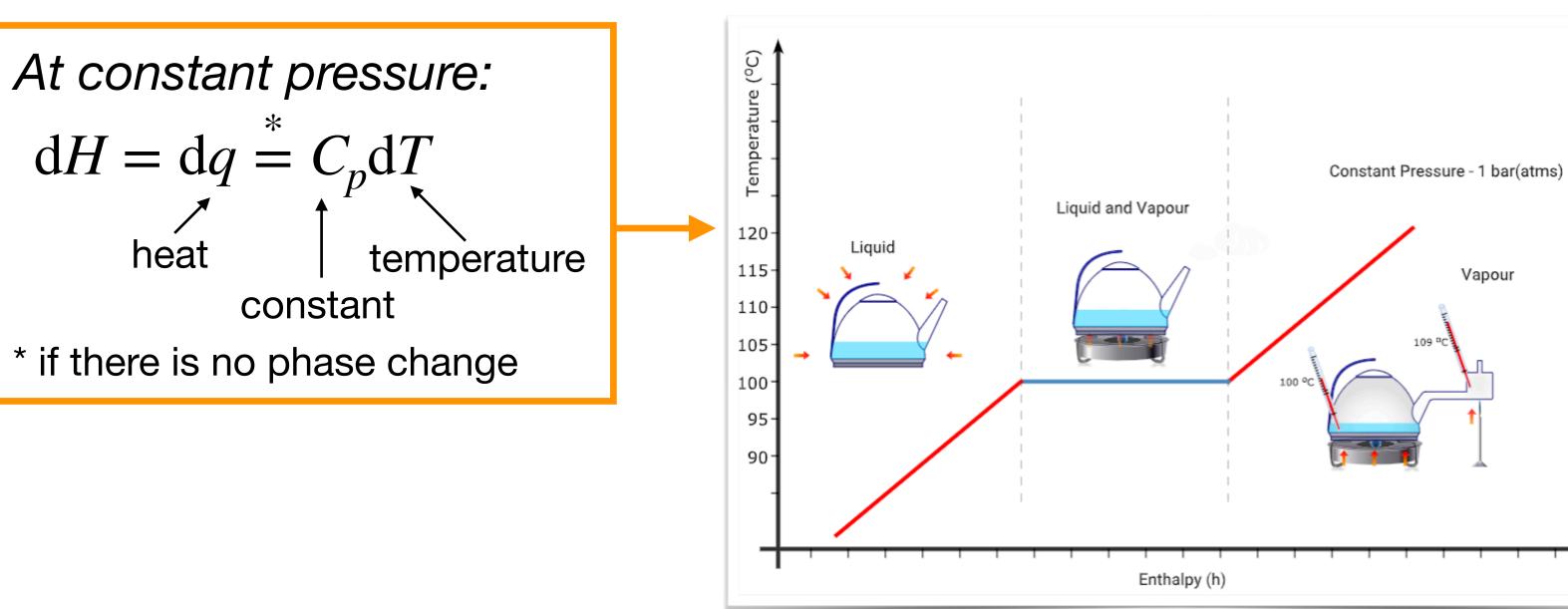
inner energy pressure



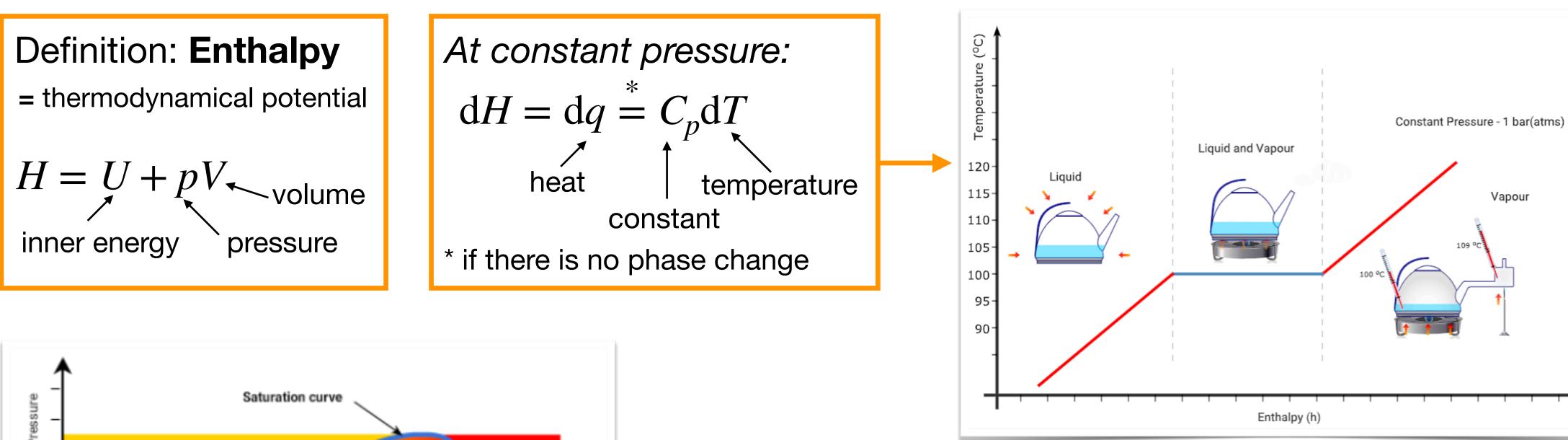


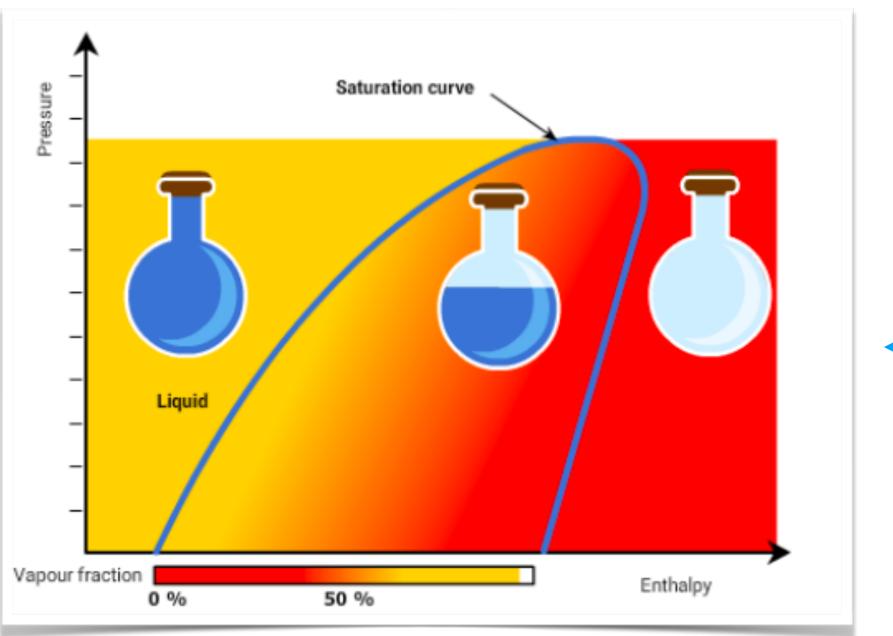
temperature











p-h diagram



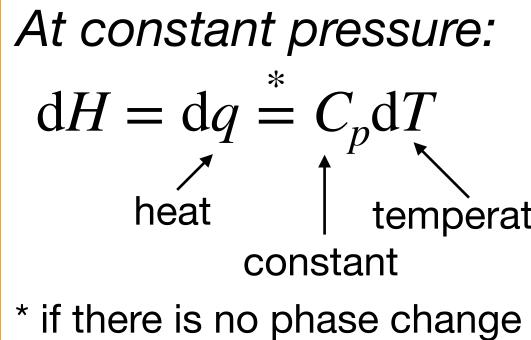
Refrigerant cycle

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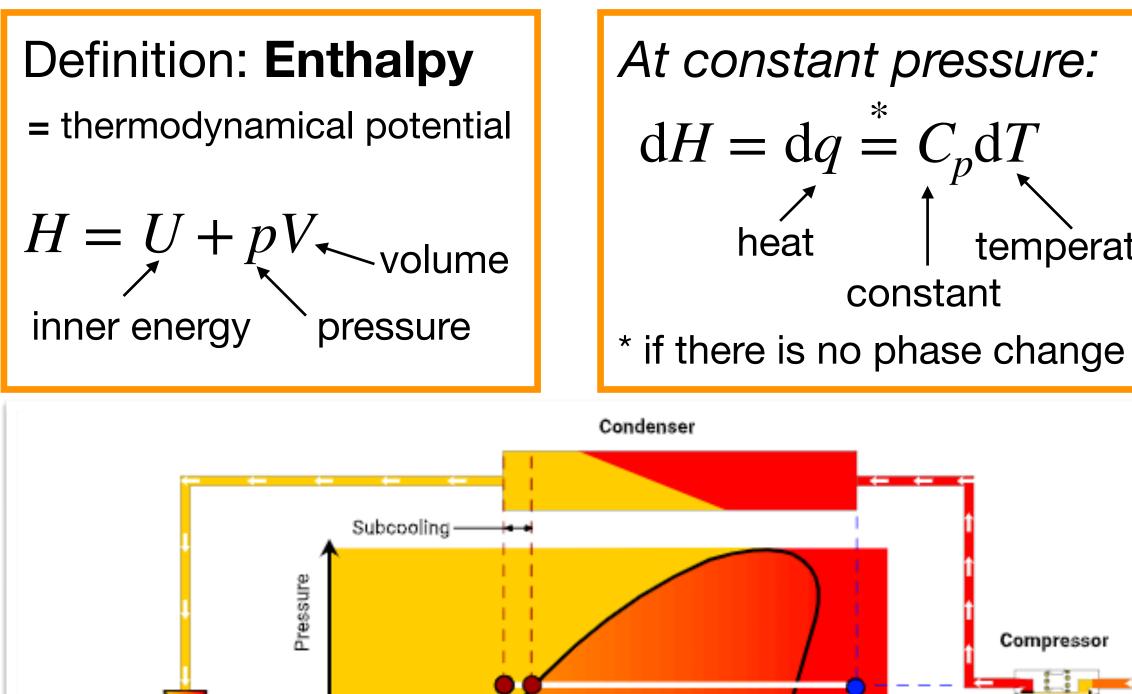
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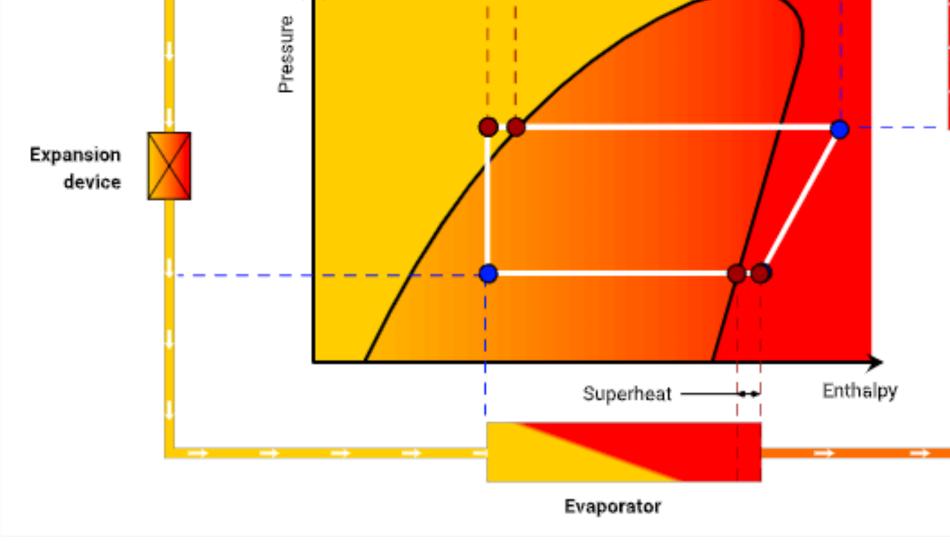
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- temperature

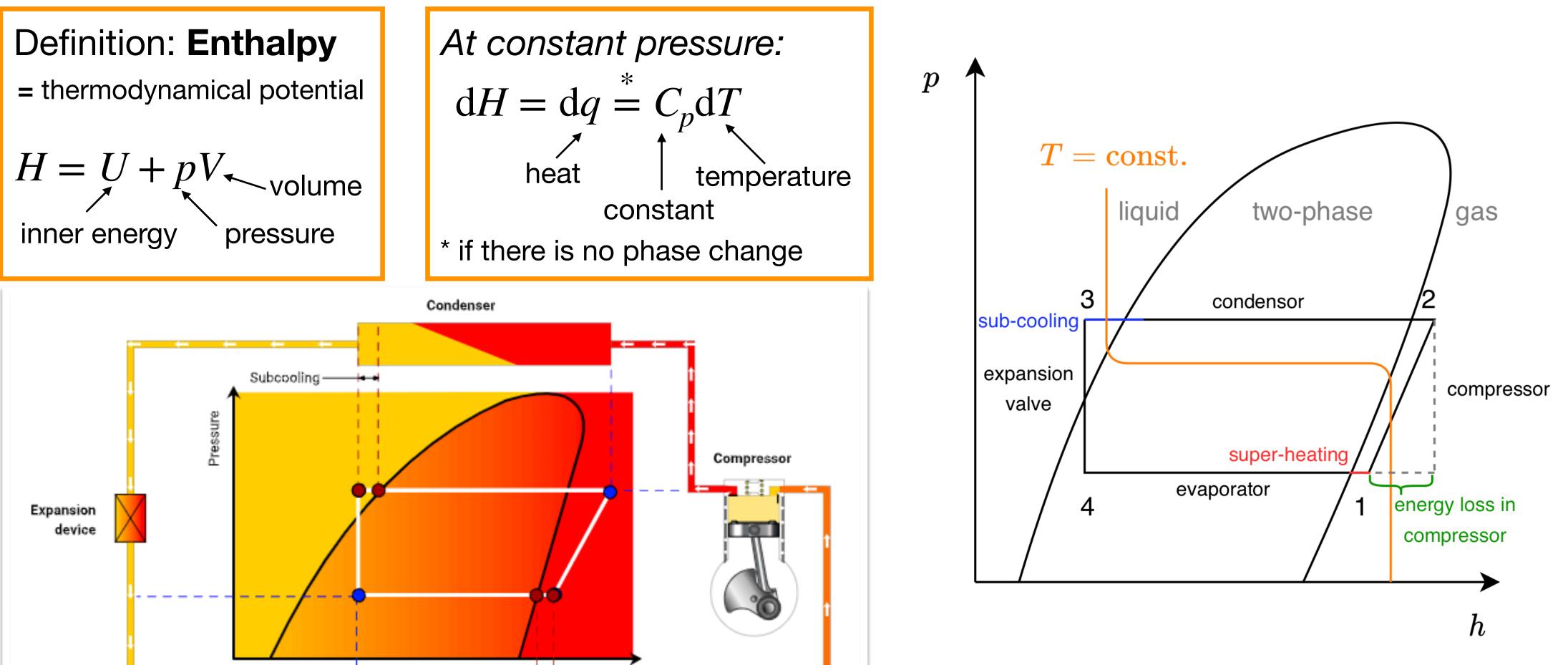
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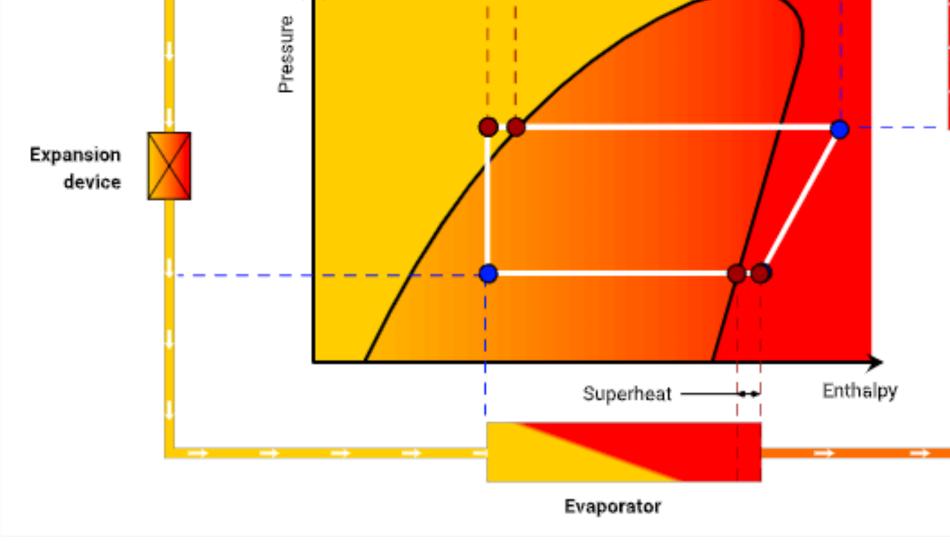




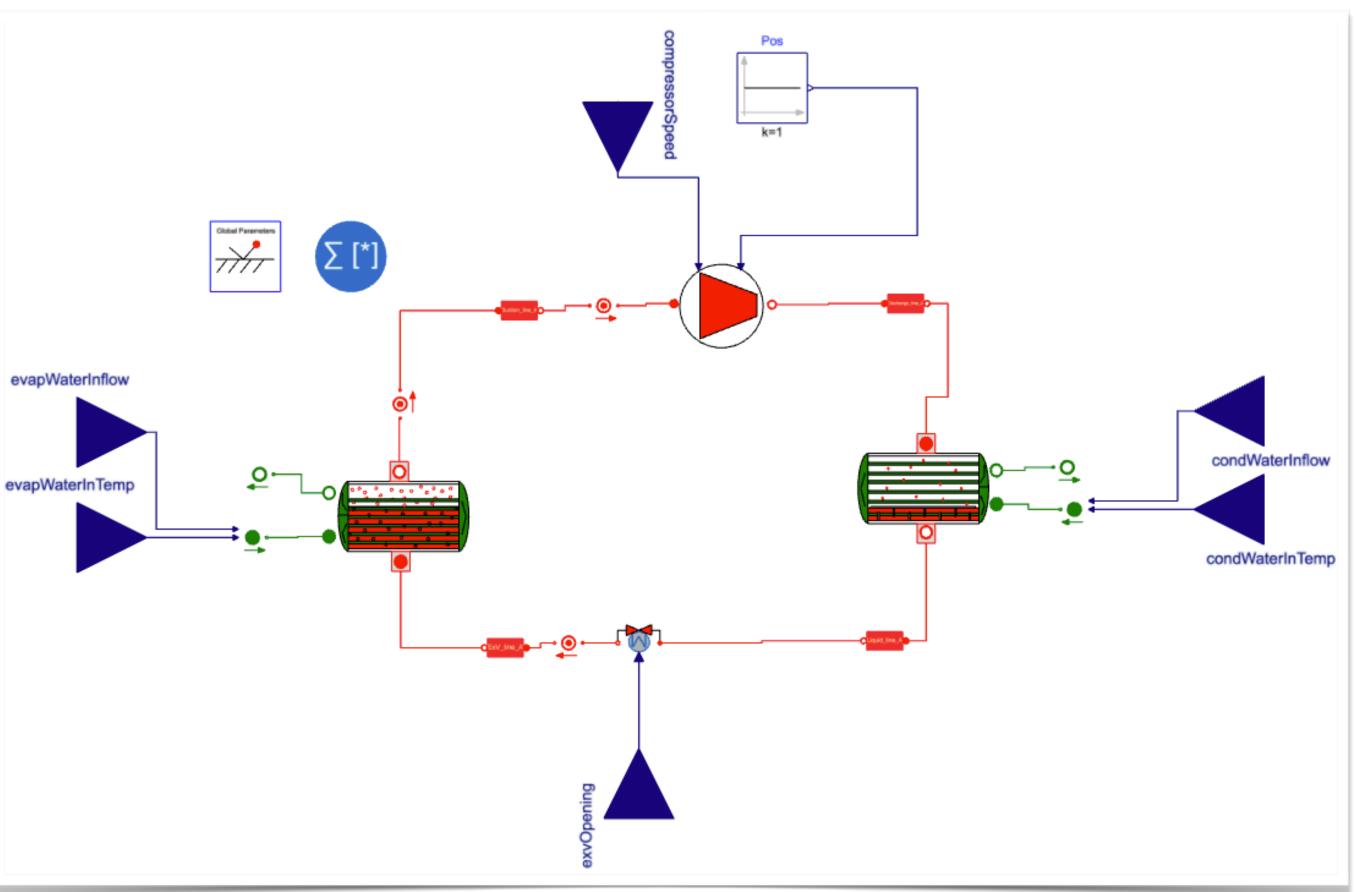
temperature Compressor

Refrigerant cycle





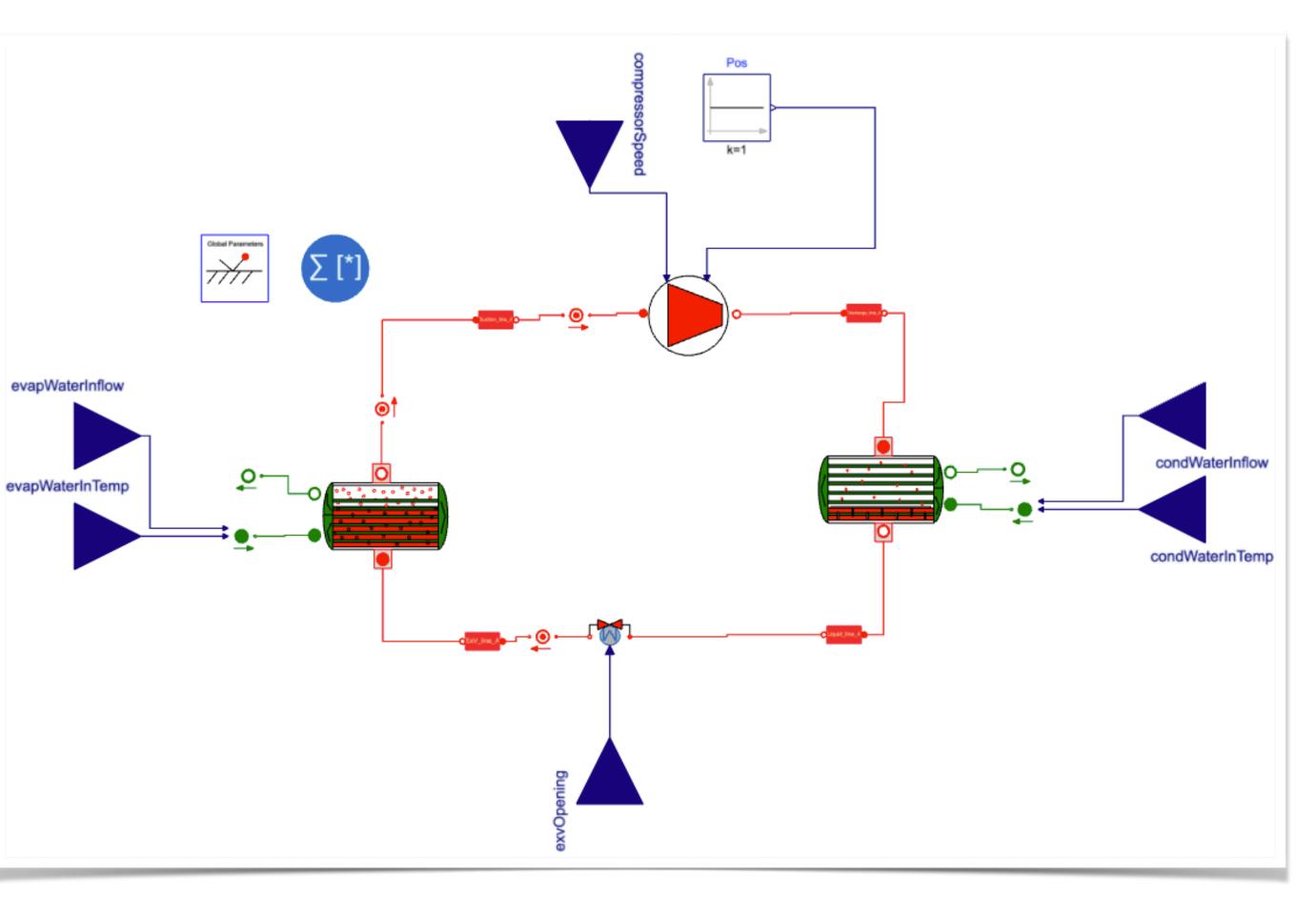
Simulation model

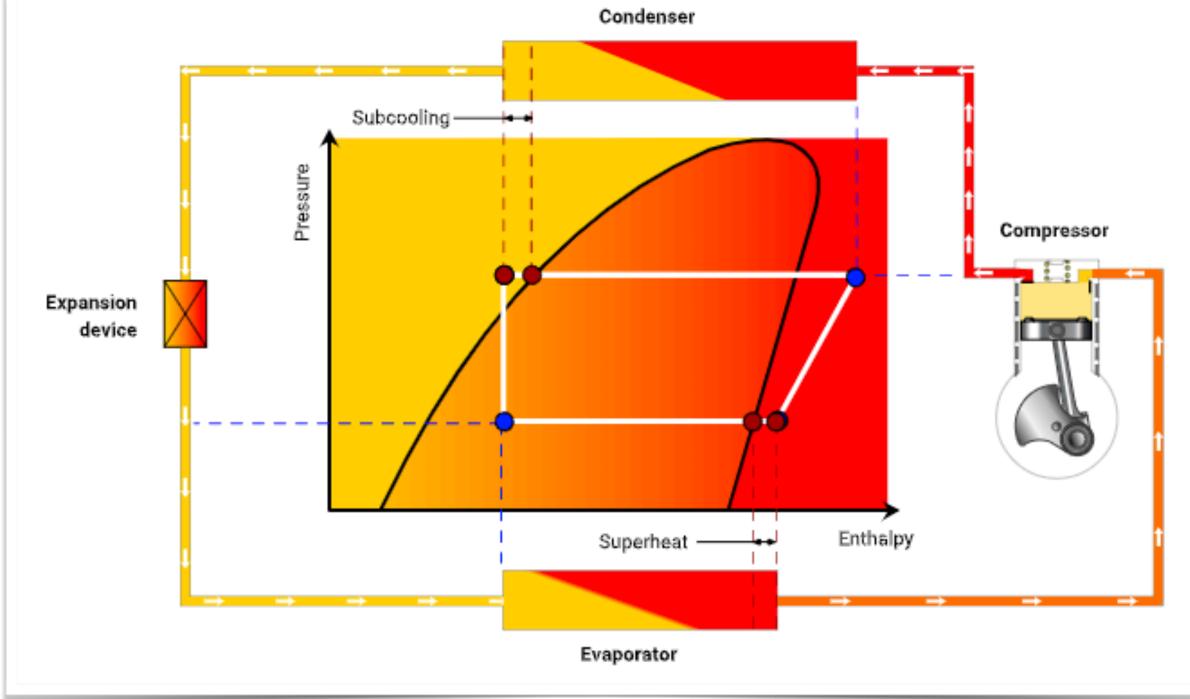


Simulation model

Complex nonlinear model, with 161 states.

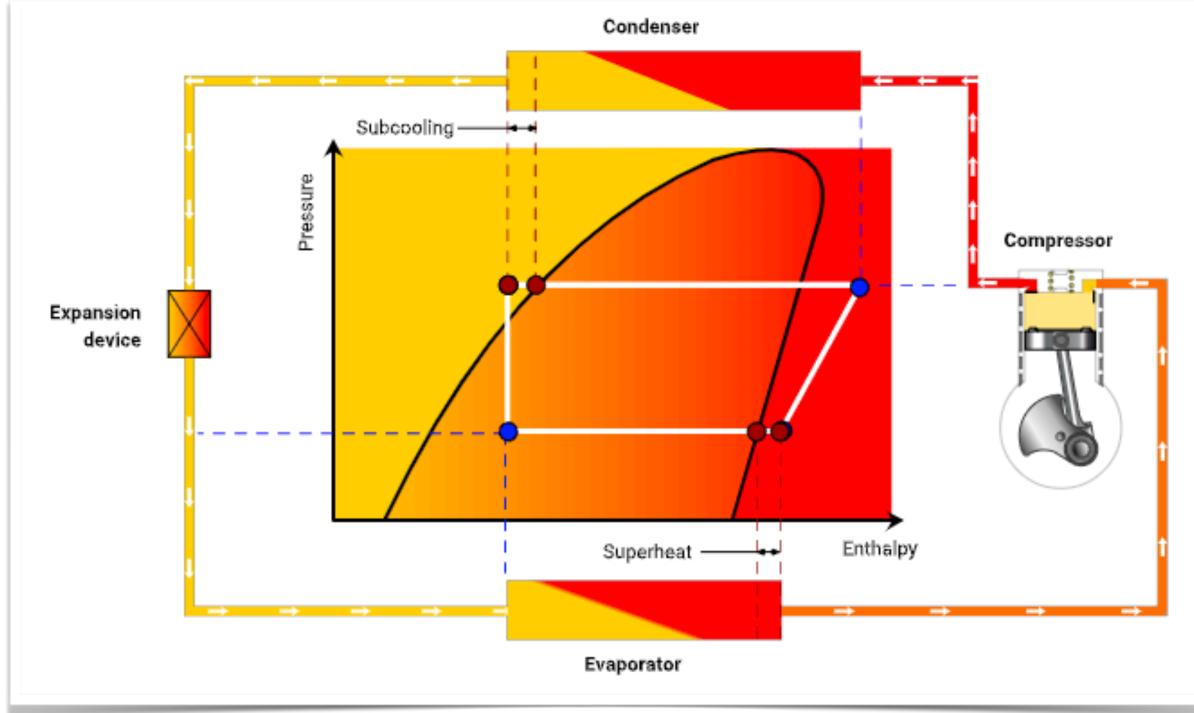
Simulations can be done in Modelon Impact or in Python with an FMU.





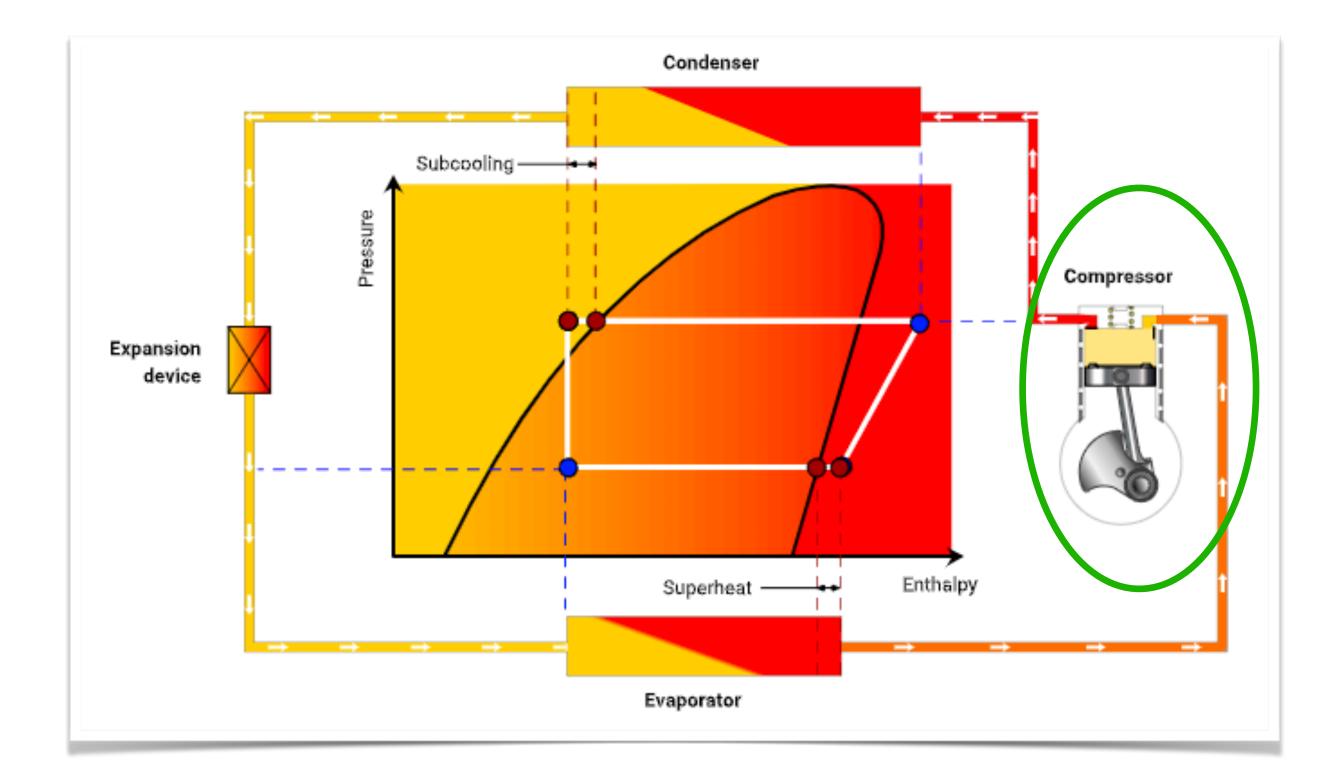


- Compressor speed
- Expansion valve opening

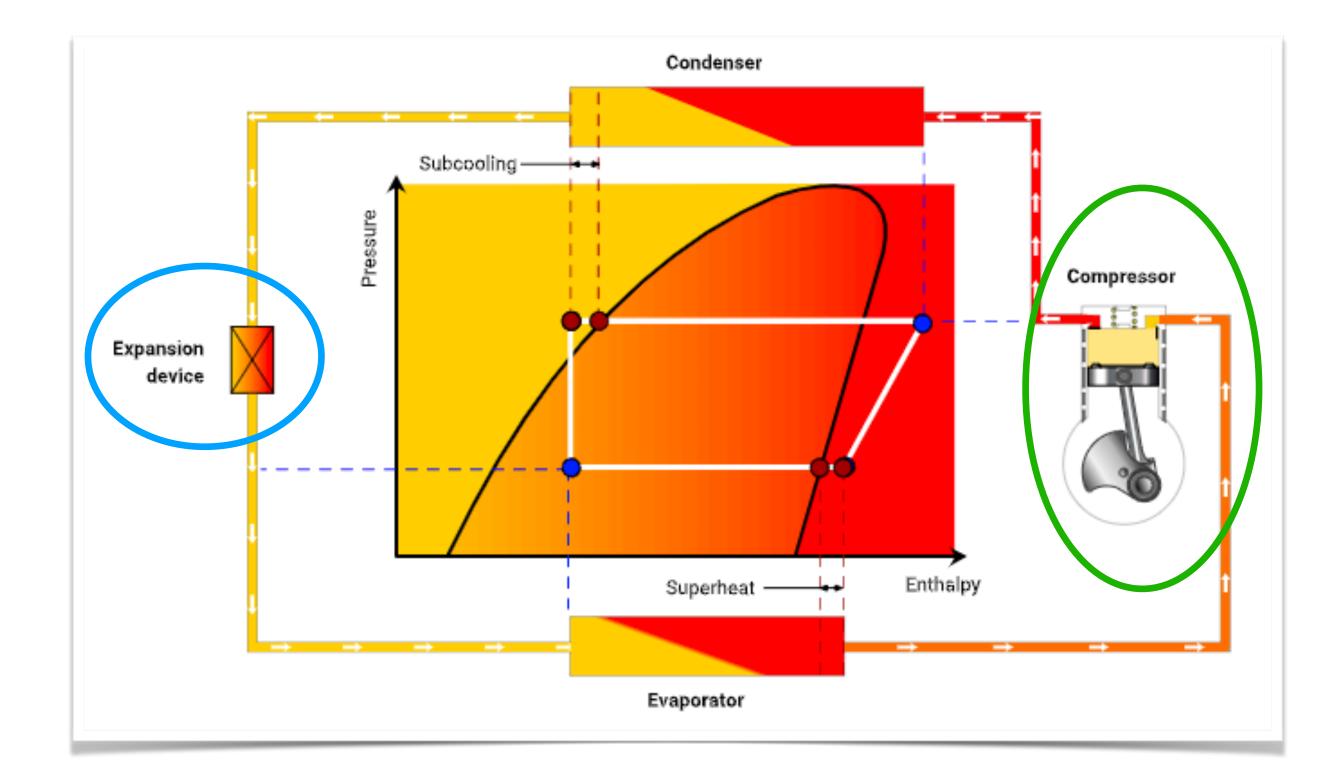




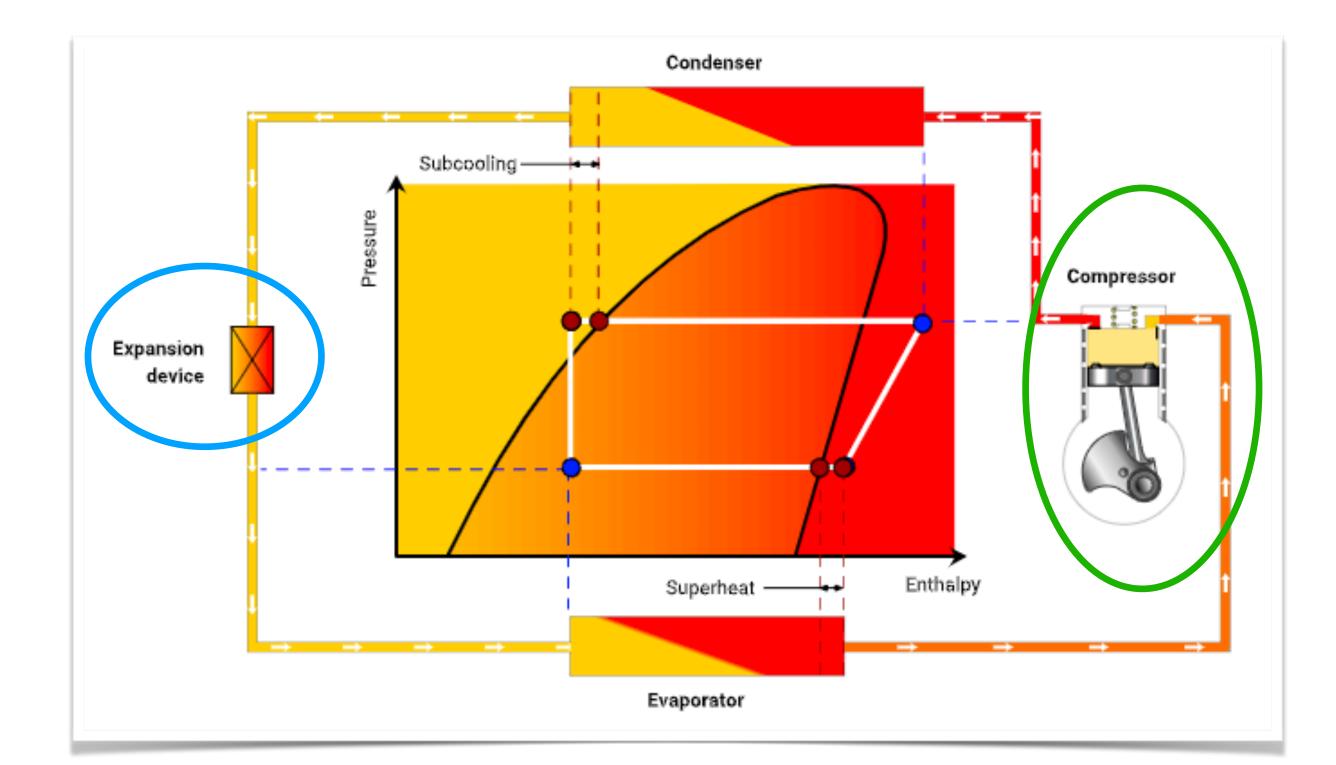
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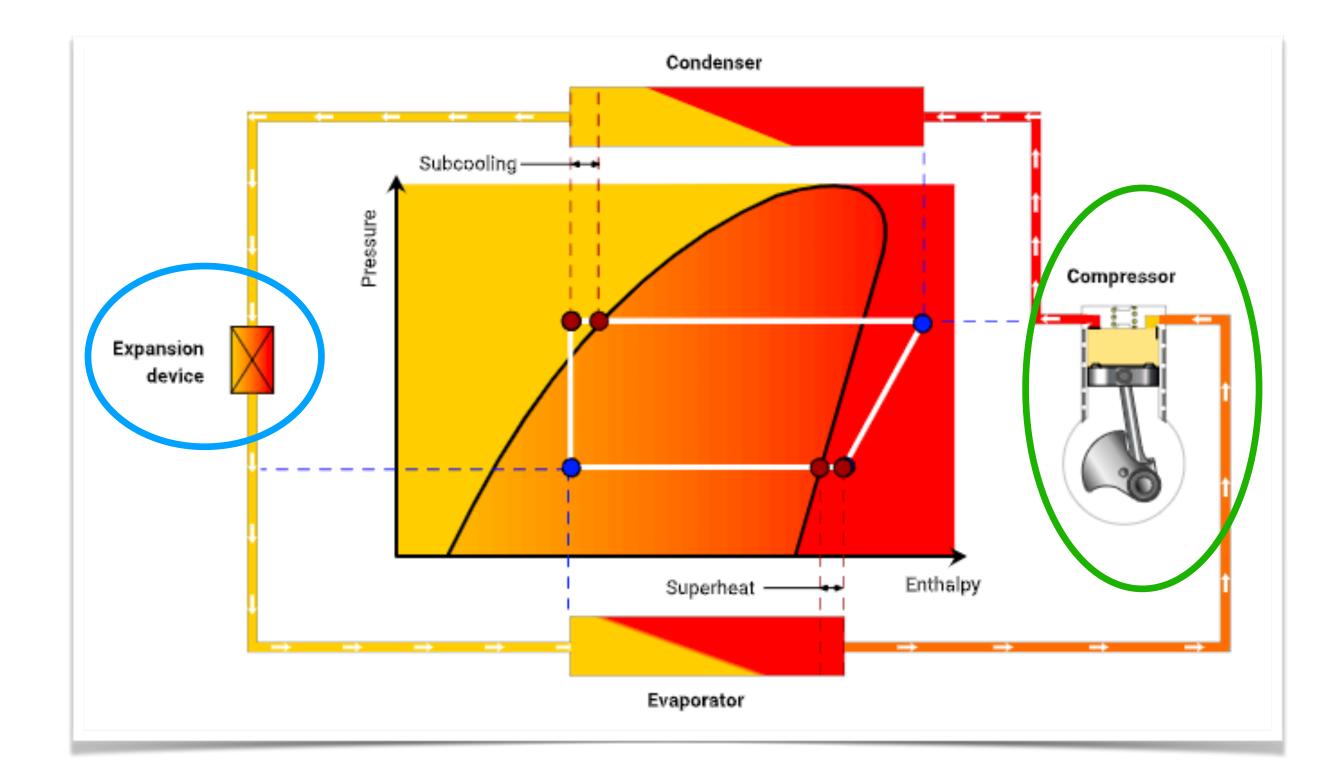
Control problem

Objectives and constraints:

- Achieve requested out-water temp
- Maximize efficiency (COP)
 - Correlated to refrigerant level in evaporator
- Satisfy constraints such as
 - Pressure limits in compressor
 - Actuator limitations



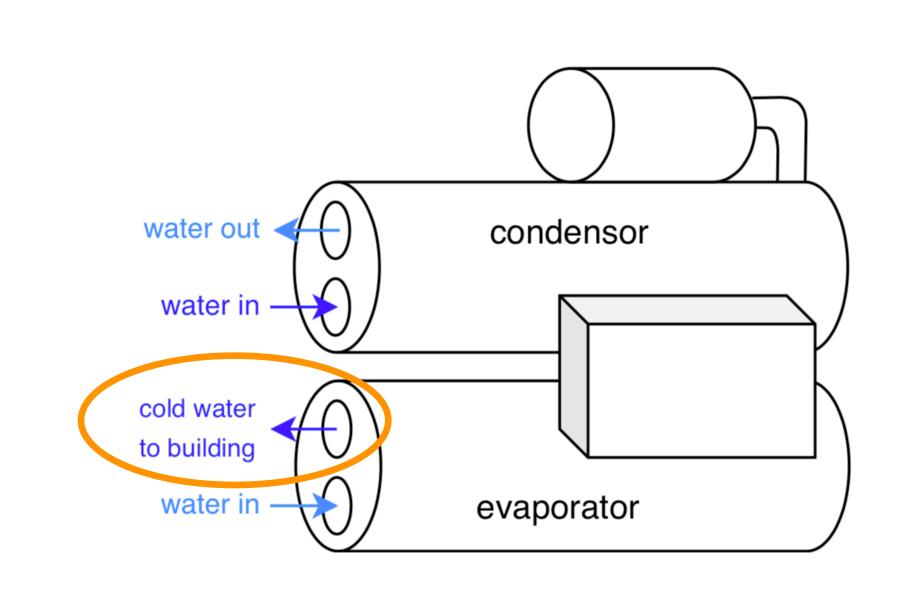
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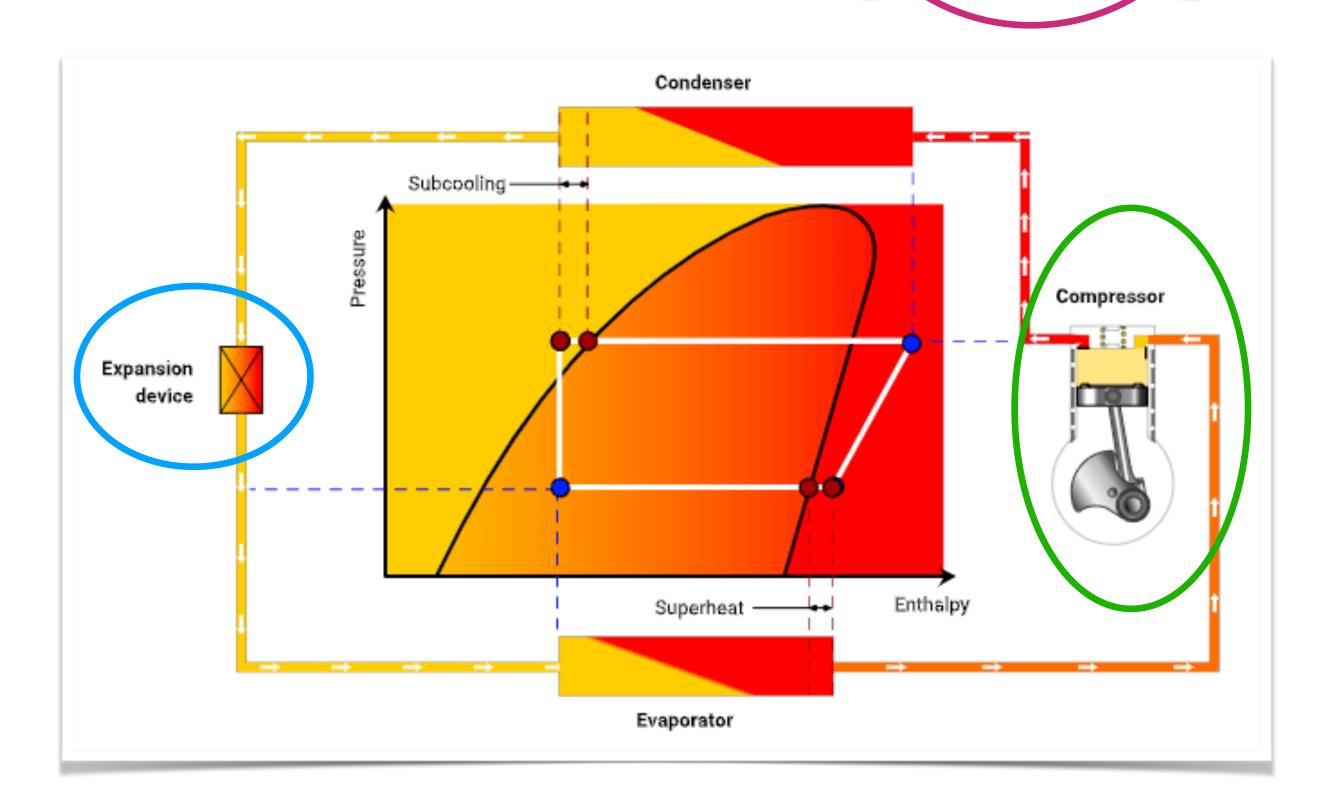




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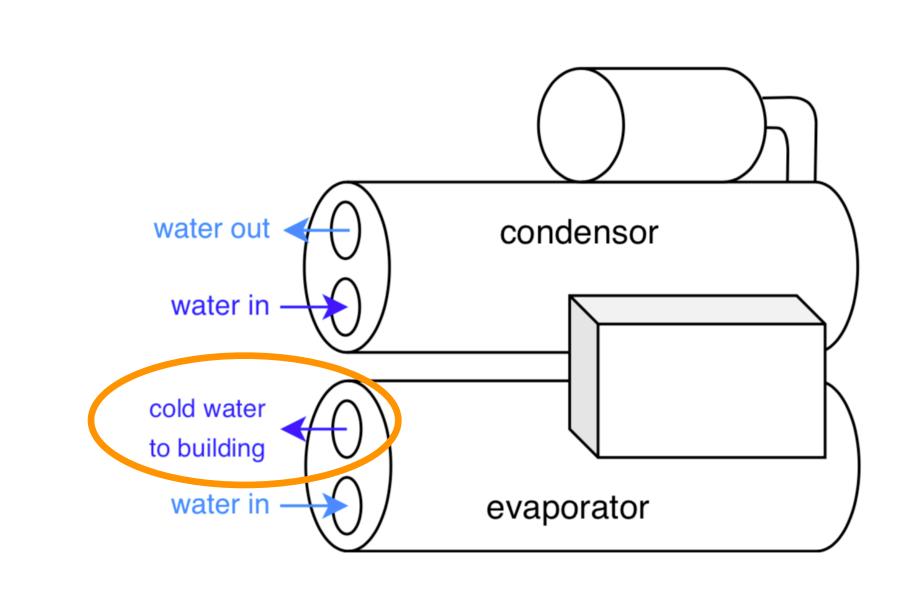
Actuators:

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with PI-controllers $C_1(s)$ and $C_2(s)$, where G(s) is a linearization of the system

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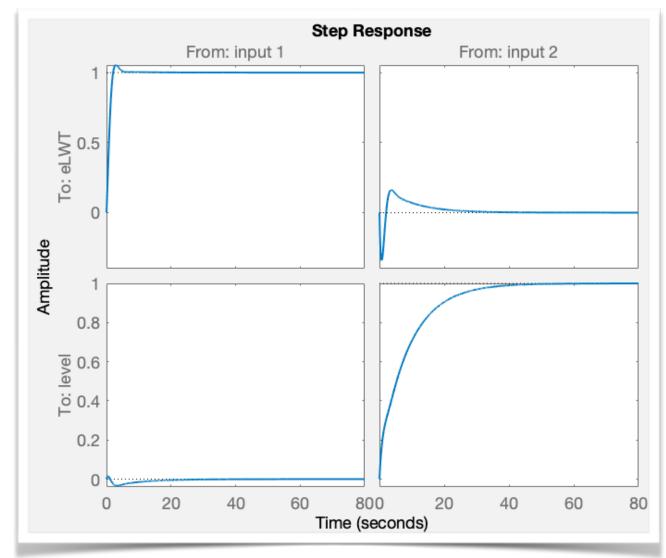
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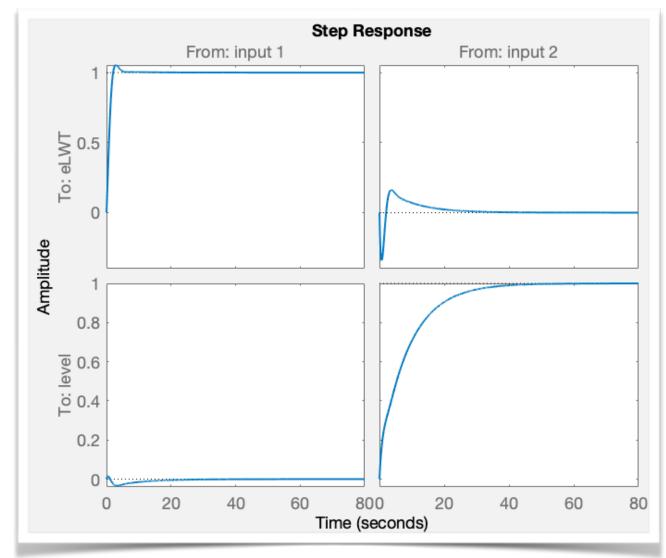
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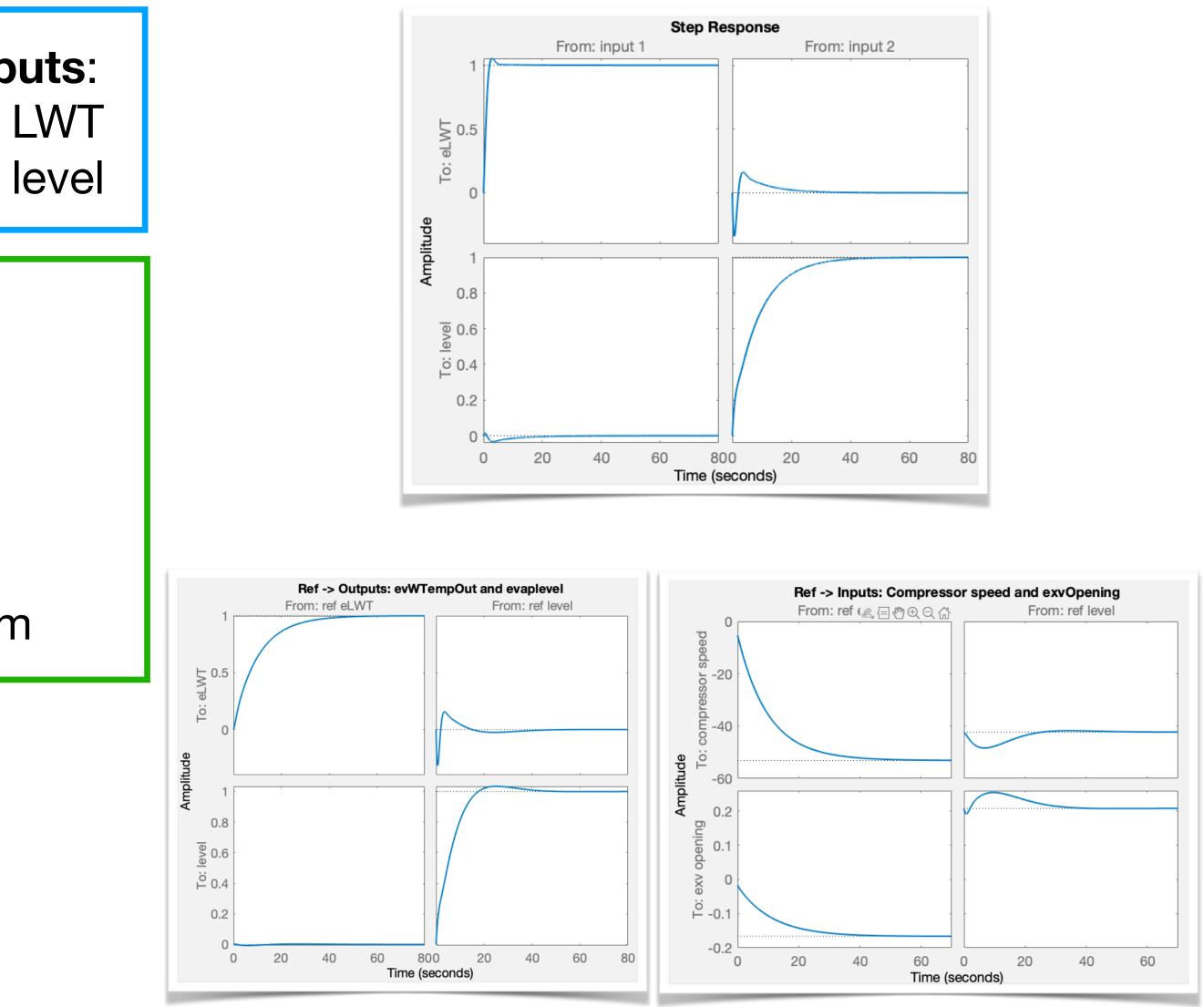
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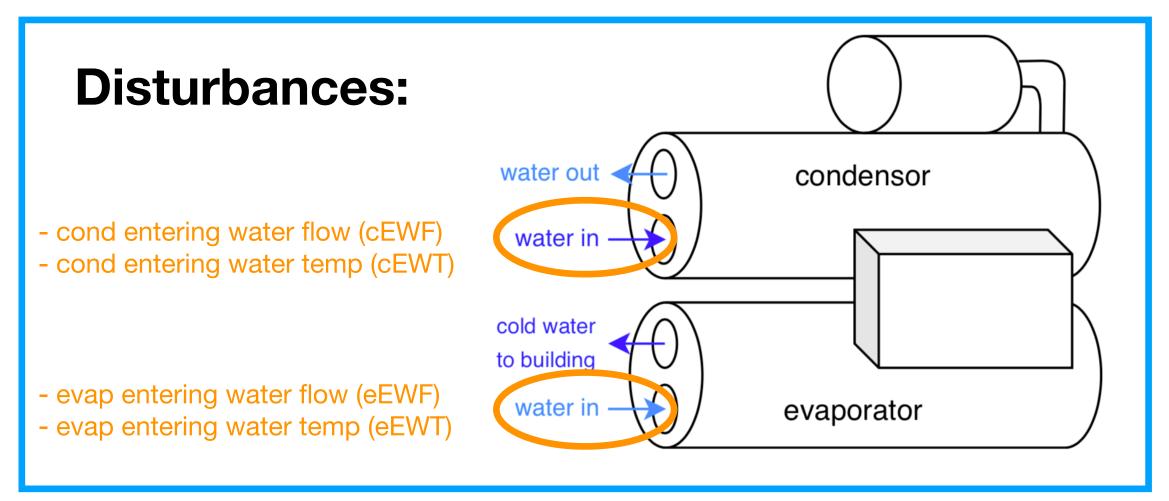


Controller tests

Controller performance for reference changes (eLWT and evap level) and disturbances

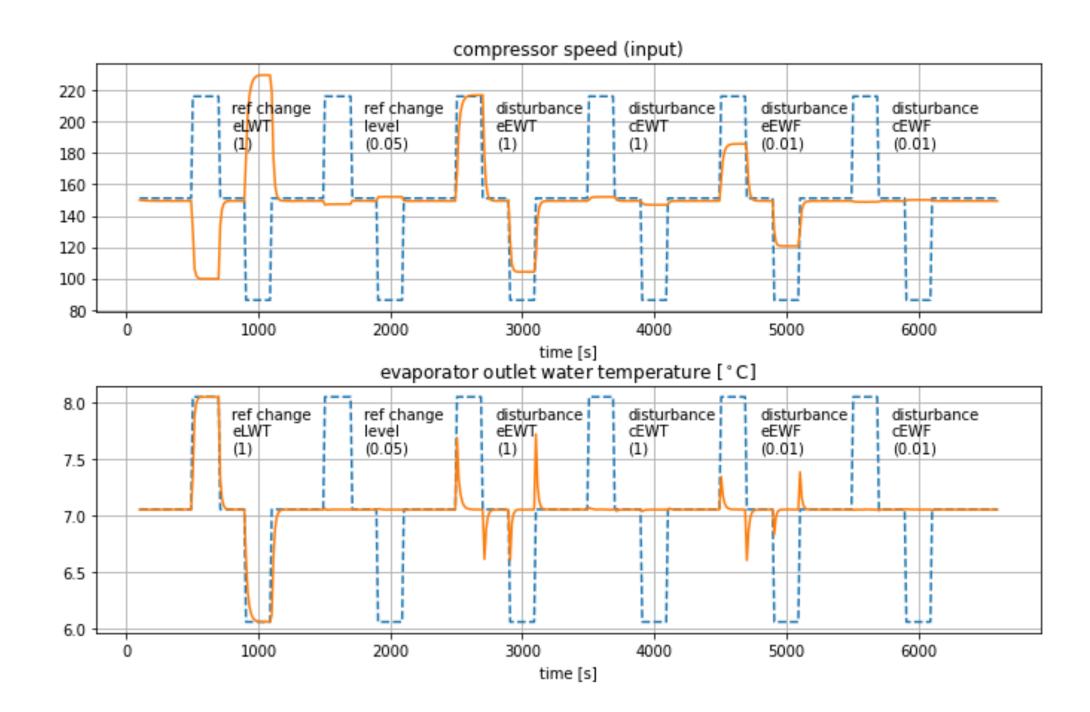
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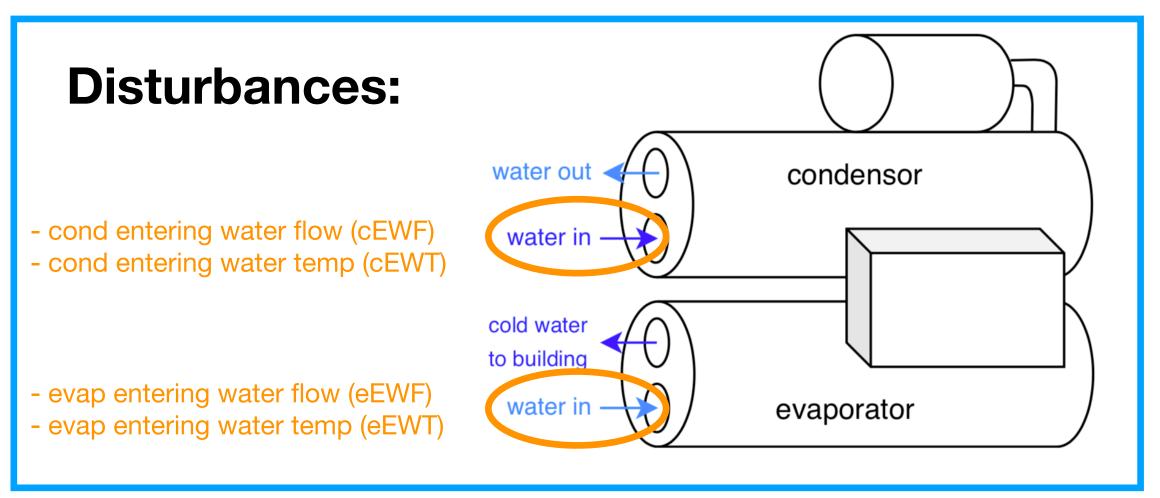
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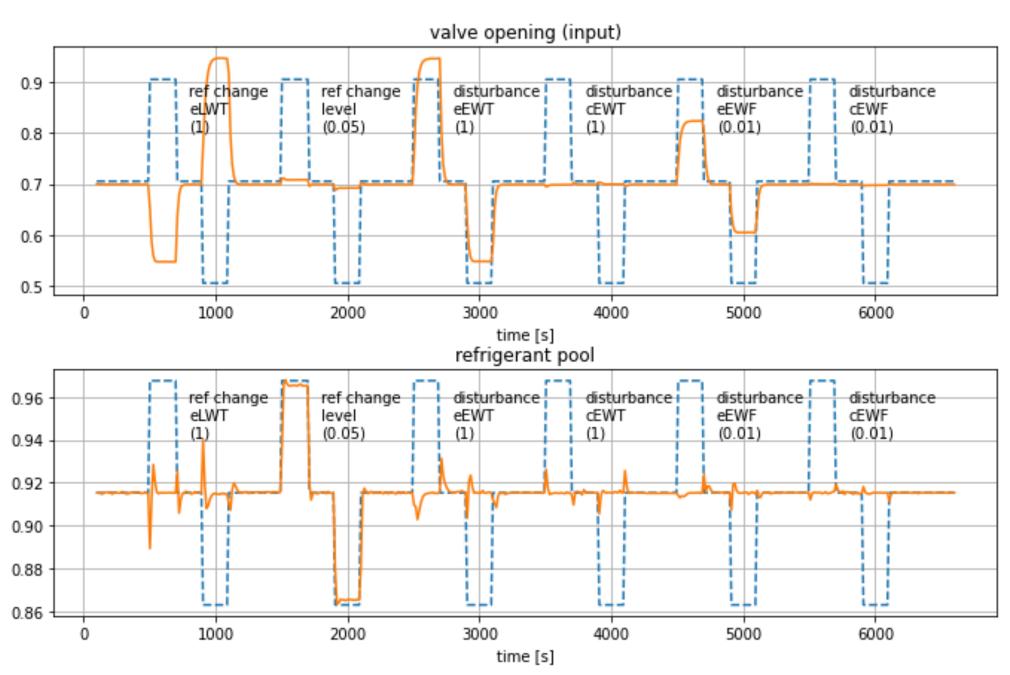


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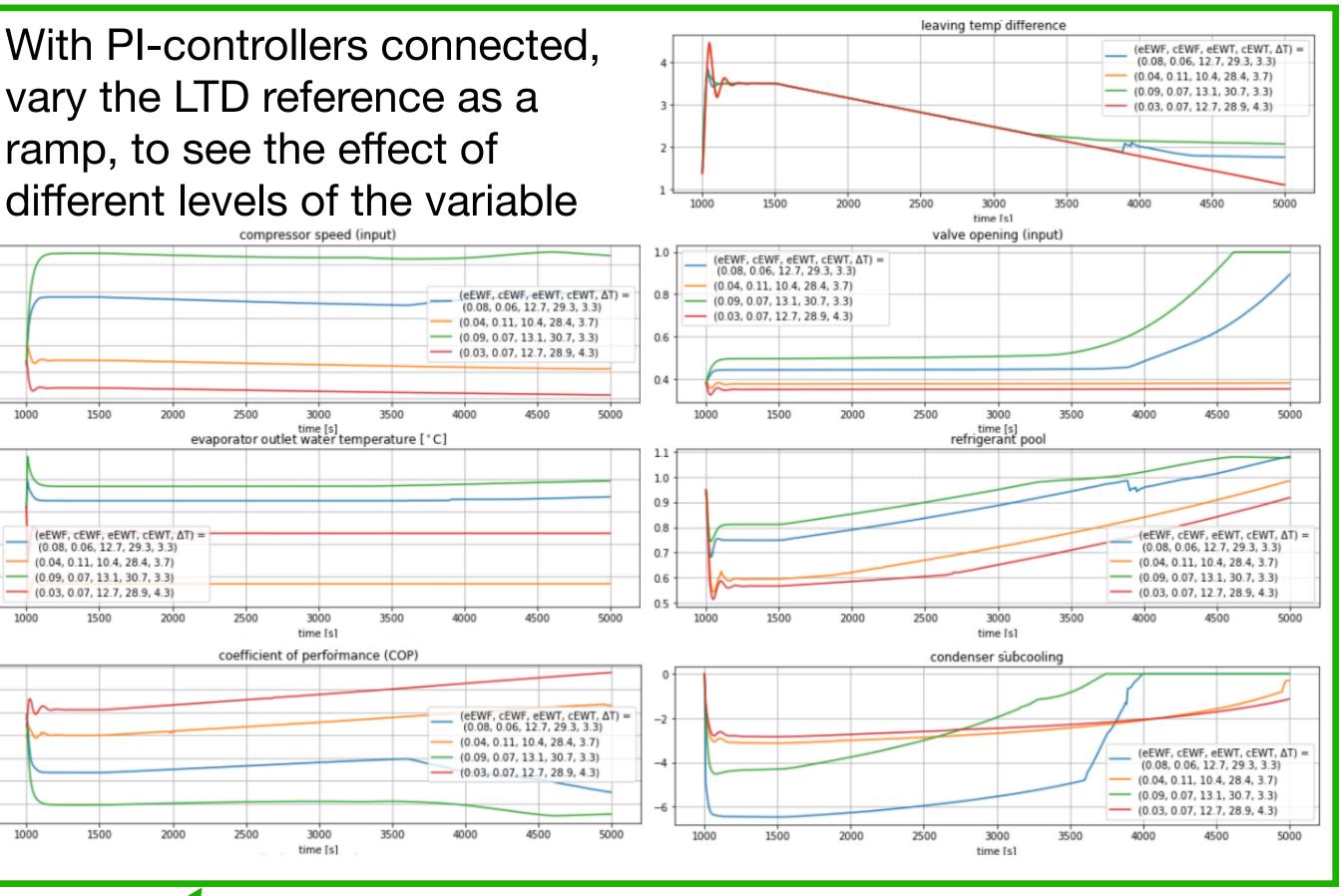
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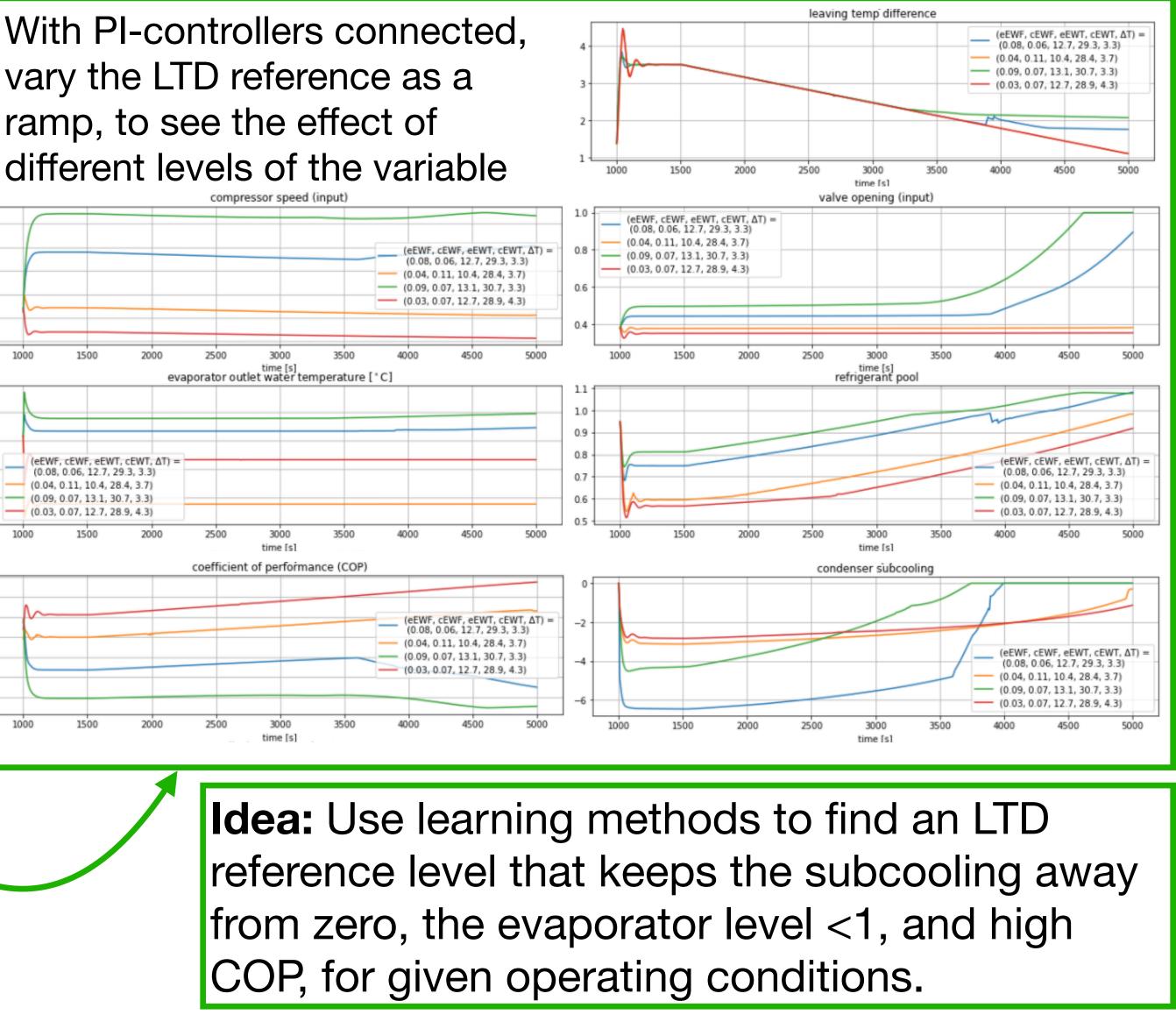
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- SVM (with and without kernels)
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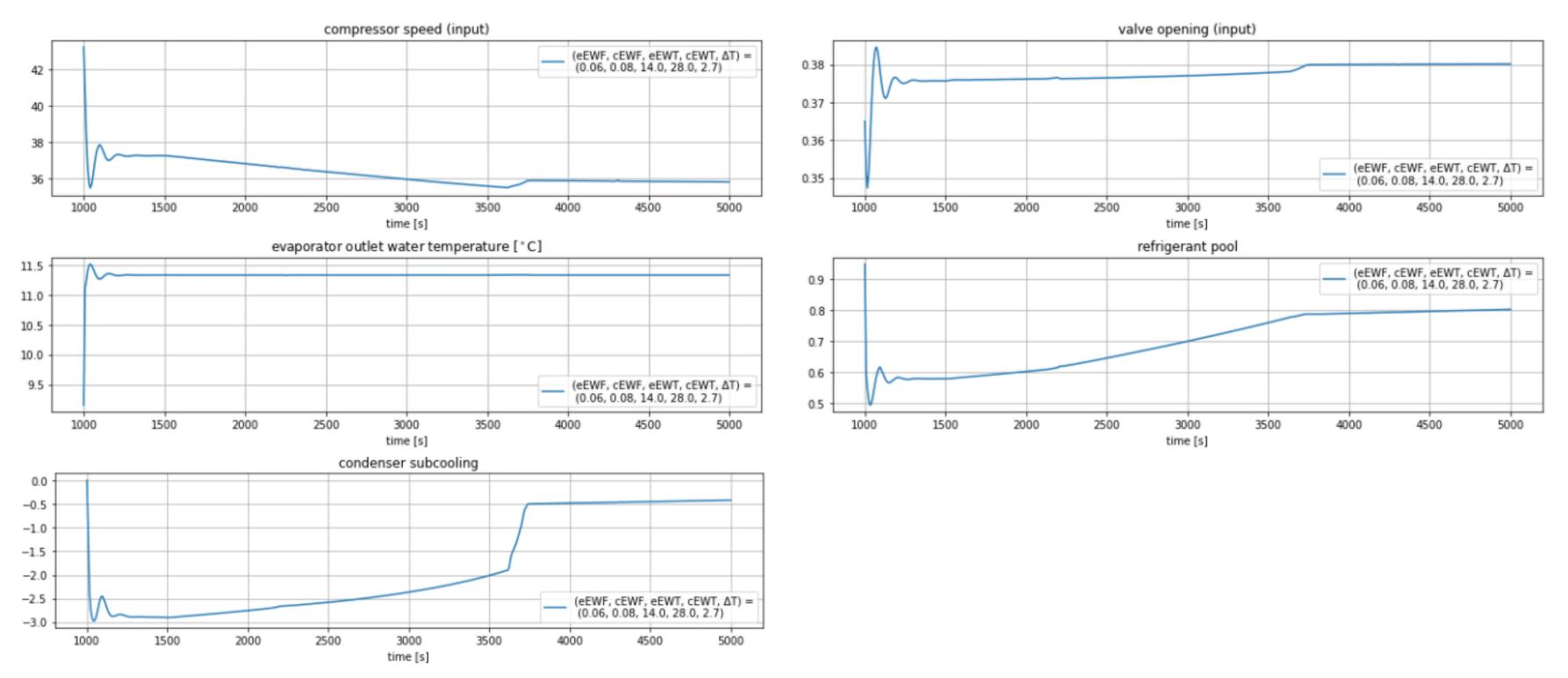
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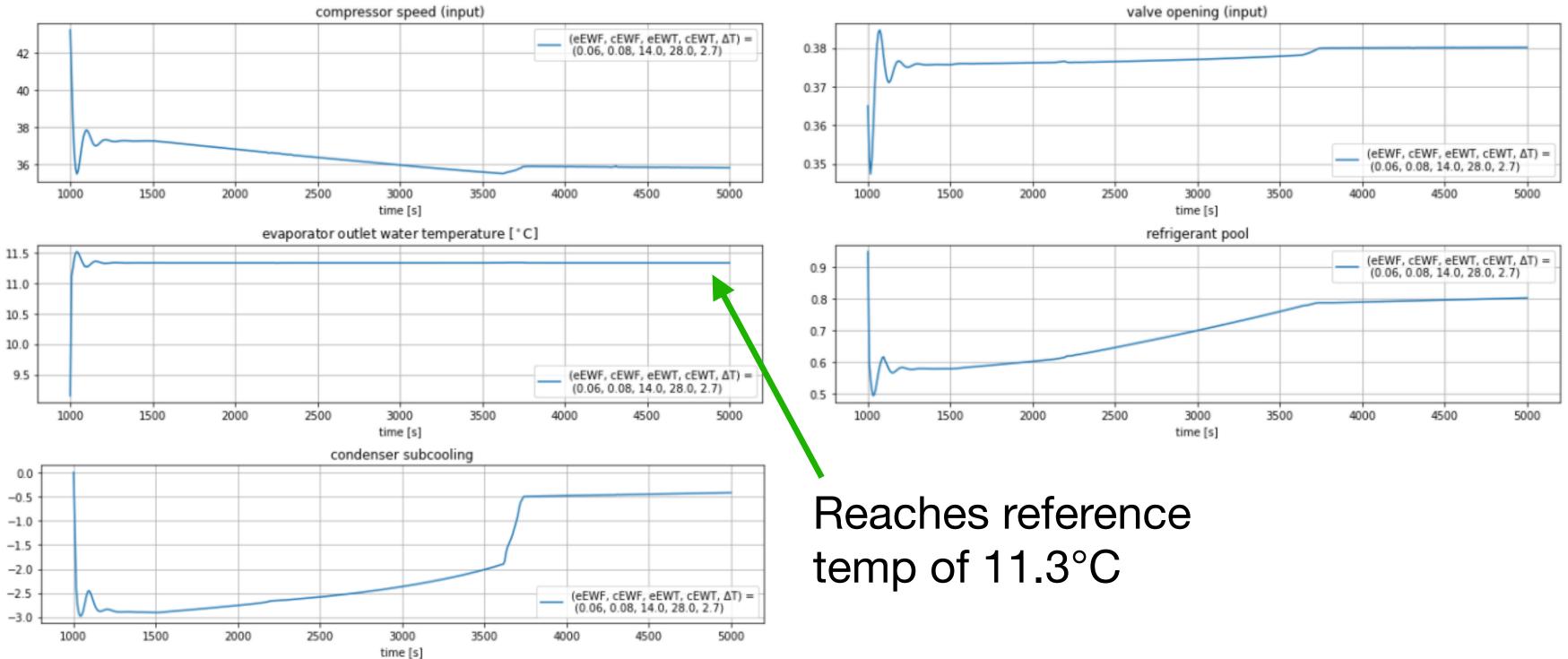
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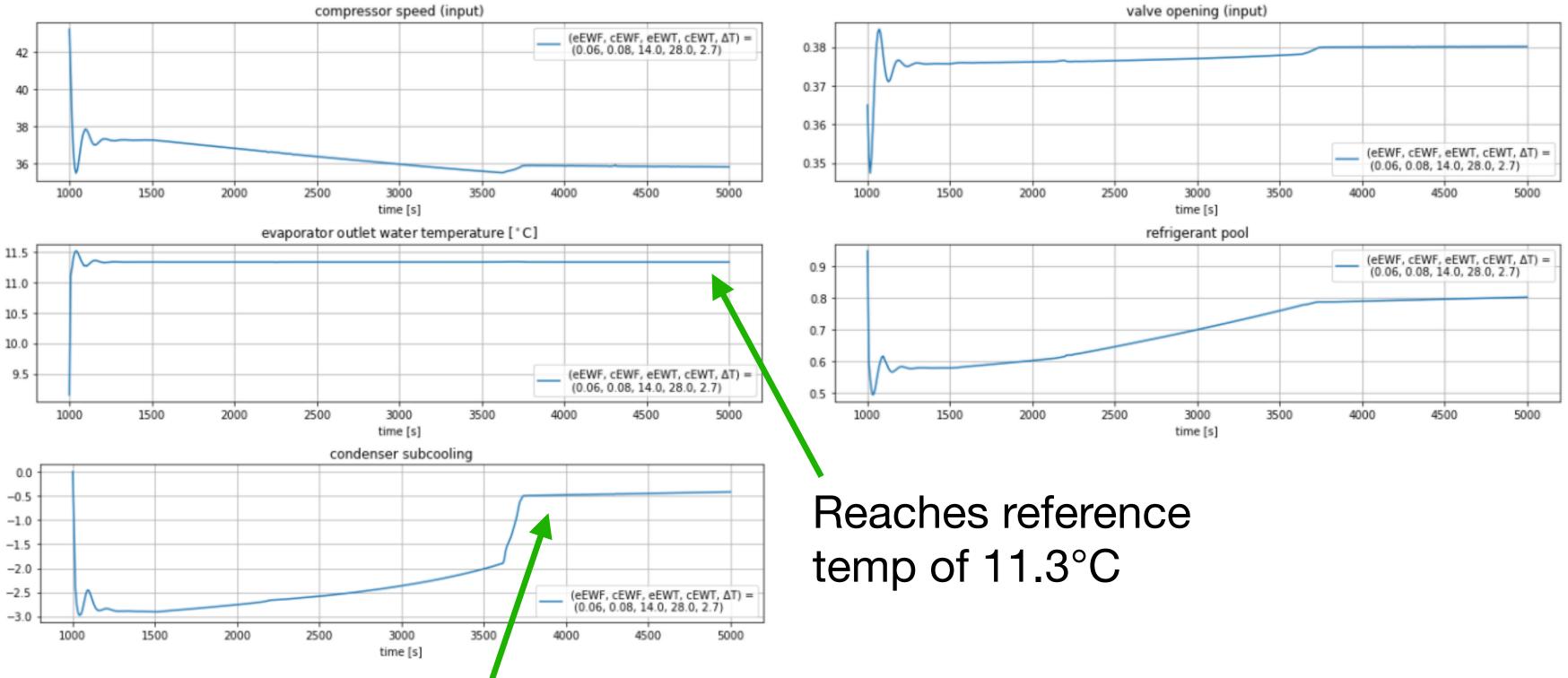
Questions

- How to best generate training data?
- Which signals are most important?

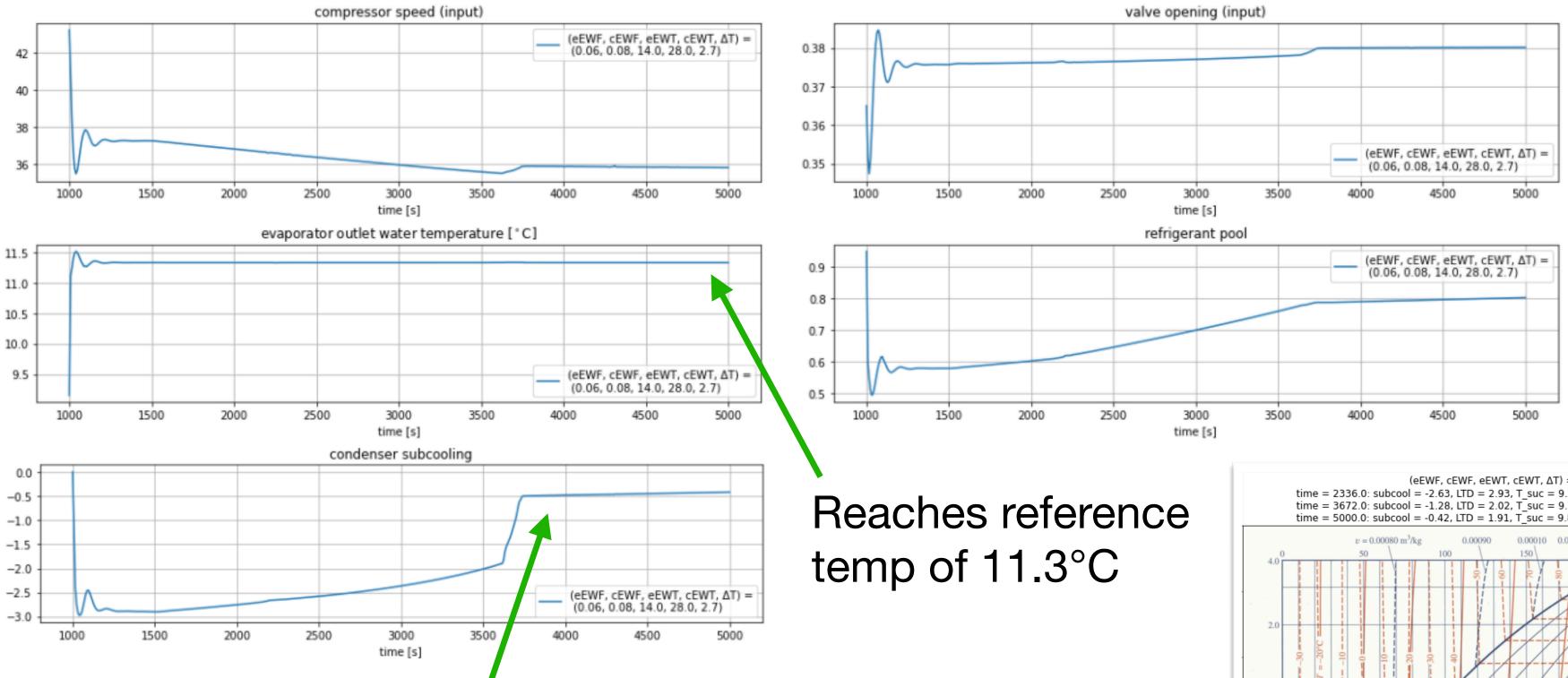




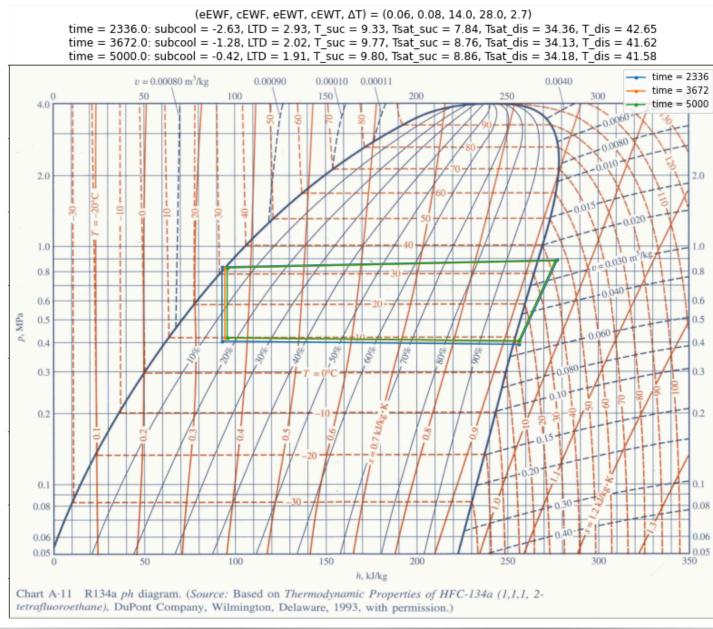


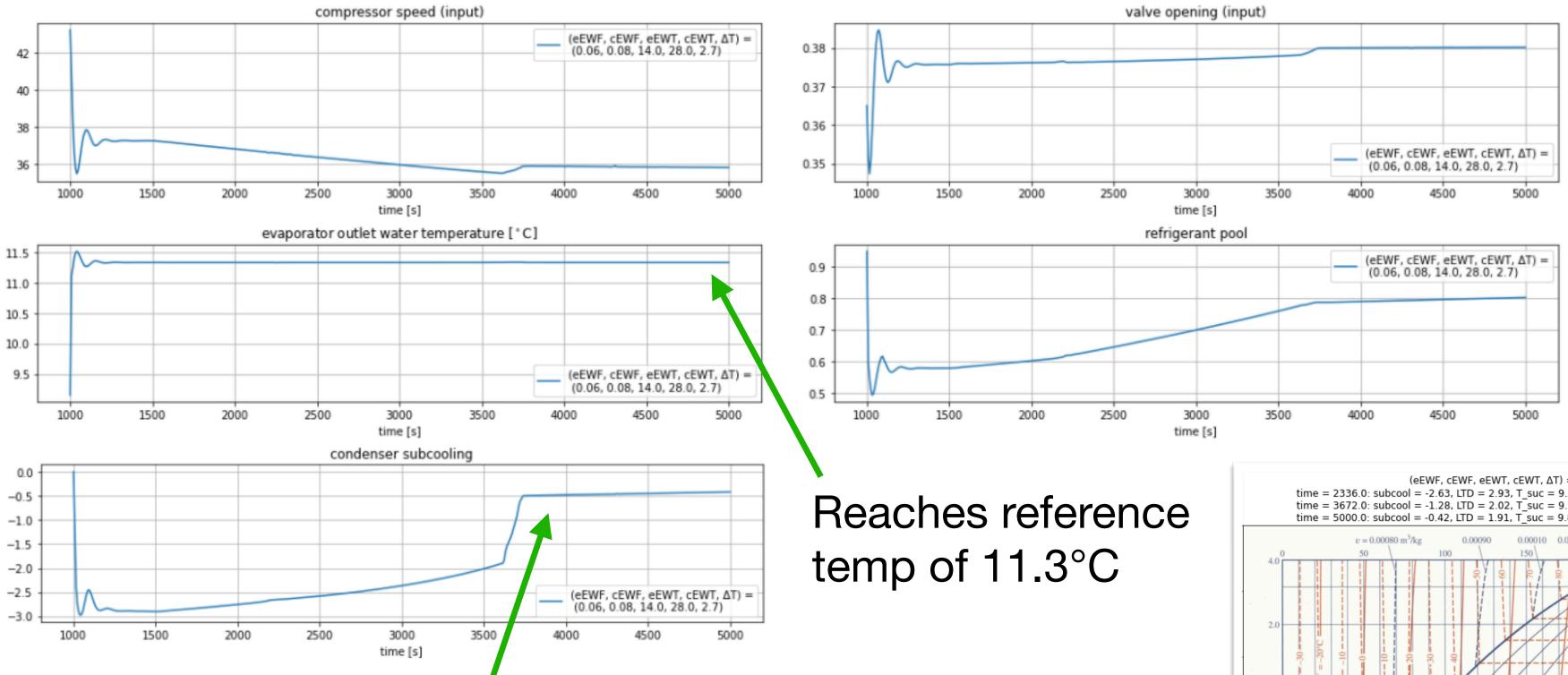


Feedback term added to counteract subcooling exceeding -0.5



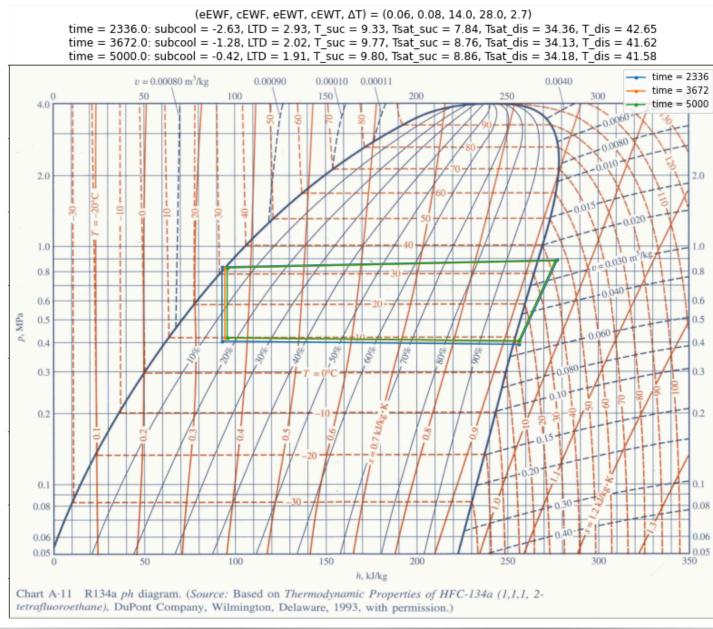
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Works well in this scenario.



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- What sensors are worth to add?
- Can we optimize the control adaptively, e.g. by some kind of dual control?

Thanks for listening!