



# **Newton's Fractal Fragility**

**Fredrik Magnusson**

Department of Automatic Control  
Faculty of Engineering  
Lund University, Sweden

October 21, 2016



# Research

Thesis defense in 4 weeks. *Numerical and Symbolic Methods for Dynamic Optimization*. Keywords:

- Modelica
- differential-algebraic equations
- dynamic optimization
- direct collocation
- block-triangular ordering



# The problem

- We want to (numerically) solve a nonlinear system of equations

$$f(x) = 0, \quad f : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

- Several possible methods. Methods based on Newton's method are most widely used.
- Fixed-point iterations are a common alternative. Properties of Newton compared to fixed-point methods:
  - + fast (second-order) convergence
  - ± requires differentiability of  $f$ , rather than contractivity
  - – expensive iterations (solve a linear system of equations)
- All algorithms of MATLAB's `fsolve` based on Newton



# The application

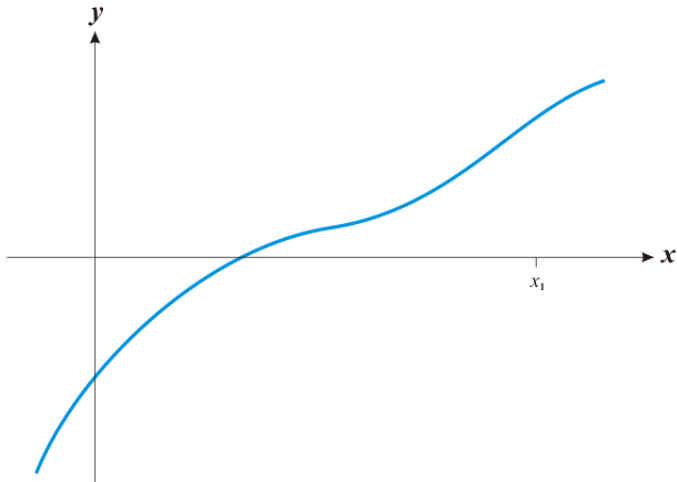
Many applications of this (maybe even more than there are applications not of this). In particular:

- Numerical optimization (KKT conditions can be transformed into nonlinear system of equations)
- Solving nonlinear differential equations (implicit integration methods)



# The method

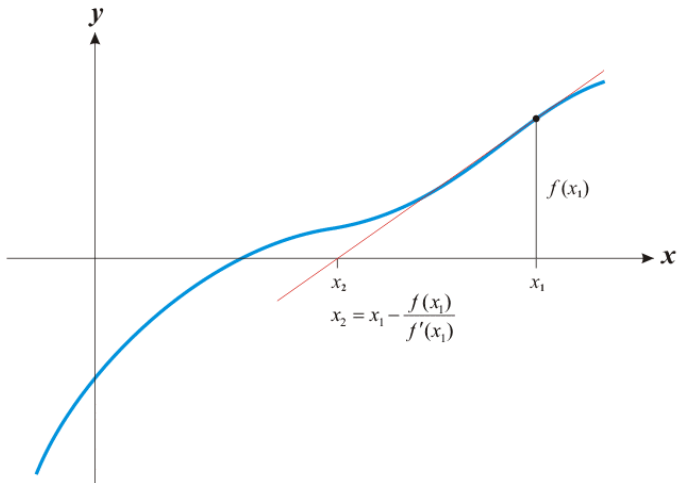
$$x_{k+1} = x_k - J^{-1}(x_k)f(x_k).$$





# The method

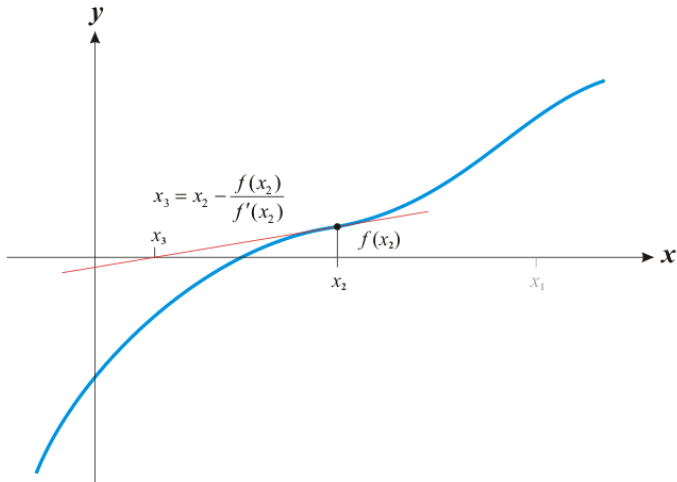
$$x_{k+1} = x_k - J^{-1}(x_k)f(x_k).$$





# The method

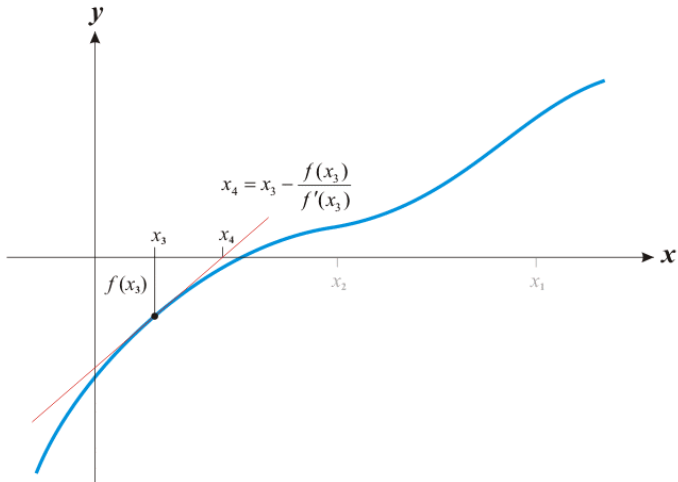
$$x_{k+1} = x_k - J^{-1}(x_k)f(x_k).$$





# The method

$$x_{k+1} = x_k - J^{-1}(x_k)f(x_k).$$

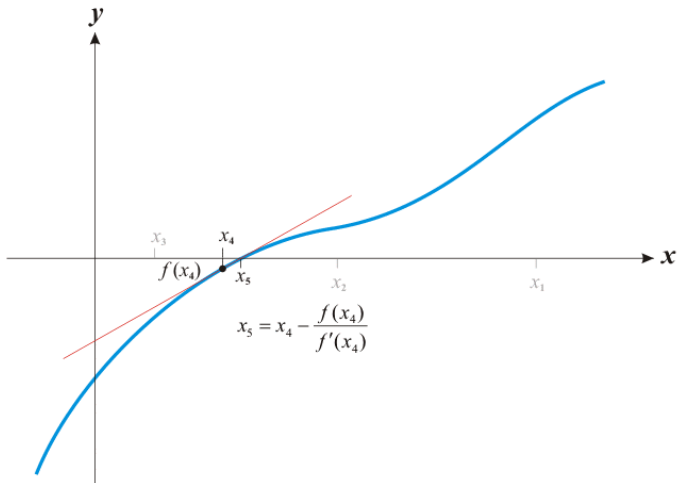






# The method

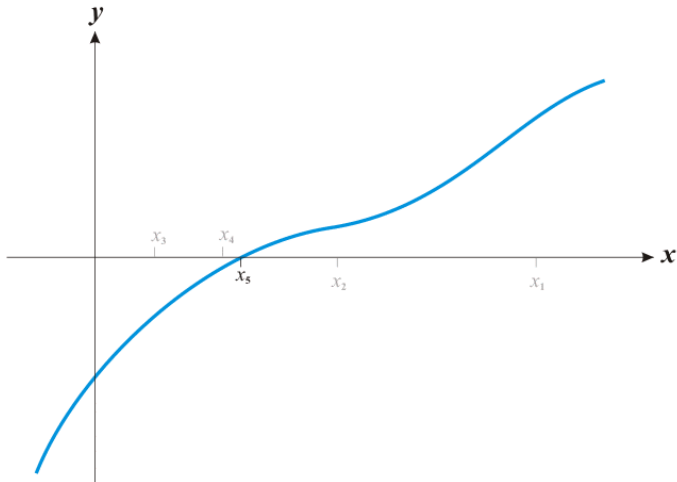
$$x_{k+1} = x_k - J^{-1}(x_k)f(x_k).$$





# The method

$$x_{k+1} = x_k - J^{-1}(x_k)f(x_k).$$





## The issue

Convergence if all of the following:

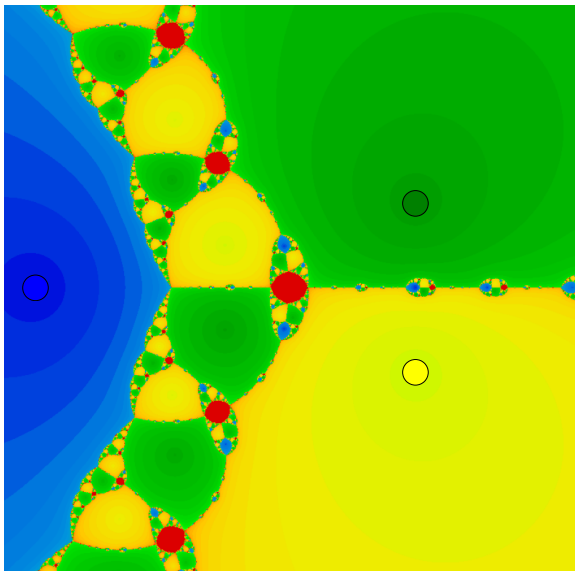
- $f$  is sufficiently regular ( $C^1$  or something along those lines)
- The initial guess is sufficiently close to the solution
- Uninteresting technicalities

Second condition is critical for many applications. Consider the very simple example  $f(z) = z^3 - 2z + 2 = 0$ .

- Two-dimensional if we let  $z \in \mathbb{C}$
- Three solutions



# Convergence regions





# Fractal

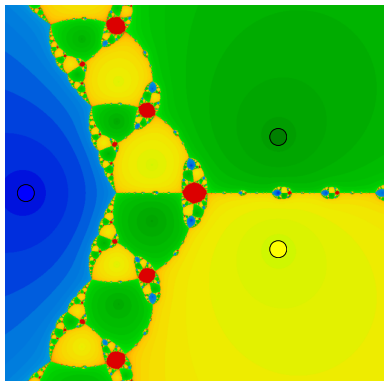
*“Beautiful, damn hard, increasingly useful. That’s fractals.”*

— Mandelbrot

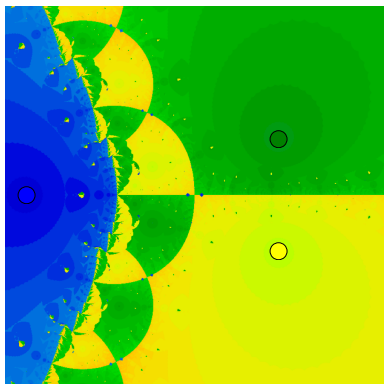
- Newton’s method generates fractals for large classes of root-finding problems
- Consequence: Exist points such that small perturbations yield unpredictable behavior
- Newton iterations can be viewed as a chaotic dynamic system
- Vanilla Newton is never used in practice. What about IPOPT?



# IPOPT convergence



Newton

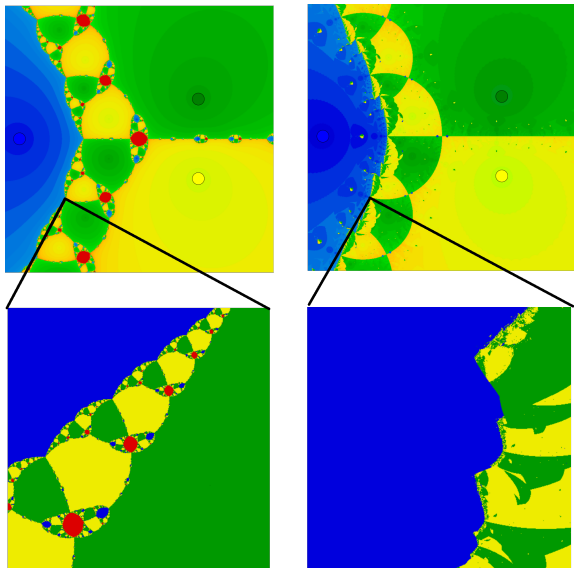


IPOPT

- + Divergence is gone
- $\pm$  Fractal?
- - Smaller region of convergence



# Fractal zoom



- Fractality of Newton is clear
- IPOPT fractal? Probably not. But probably chaotic.



## Pendulum on a cart

```
optimization pendulum(  
    objective=finalTime, startTime=0,  
    finalTime(free=true, min=0.1, max=10,  
              initialGuess=3.371260290708))  
  
parameter Real l = 0.345;  
parameter Real lact = 0.4;  
parameter Real g = 9.81;  
Real p(start=-0.8, fixed=true);  
Real p_dot(start=0, fixed=true);  
Real theta(start=0, fixed=true);  
Real theta_dot(start=0, fixed=true);  
Real x_p;  
Real y_p;  
input Real a_ref_dot(free=true);  
Real a_ref(start=0, fixed=true);
```





# Perturbations

- Perturbed initial guess are rarely a problem in practice
- However, problems themselves are often “perturbed”, with the same consequence!
  - Add a variable and trivial equation, e.g.,  $y = 3$
  - Reorder the equations/variables
  - Leads to different computations on the order of  $\epsilon_{\text{mach}} \implies$  can knock Newton off course



# Conclusions

- Newton's method is not robust
- Professional implementations only partially resolve the issue
- Practical concern for many applications. Insufficient awareness!
- But at least you can make pretty pictures



# The end

